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# Agent-Based Modelling in Pharo Using Cormas

Oleksandr ZAITSEV

CIRAD, UMR SENS, MUSE, Université de Montpellier, France

[oleksandr.zaitsev@cirad.fr](mailto:oleksandr.zaitsev@cirad.fr)





CIRAD is the French agricultural research and cooperation organization working for the sustainable development of tropical and Mediterranean regions.

# My Objectives



Inform you about ABM and Cormas



Get you **excited** about the cool things  
that we can do with it



Encourage you to **participate** in our effort



**Part 1:**

# Agent-Based Modelling

# Let's look at the Birds



<https://youtu.be/X0sE10zUYyY>

# Central Questions of ABM

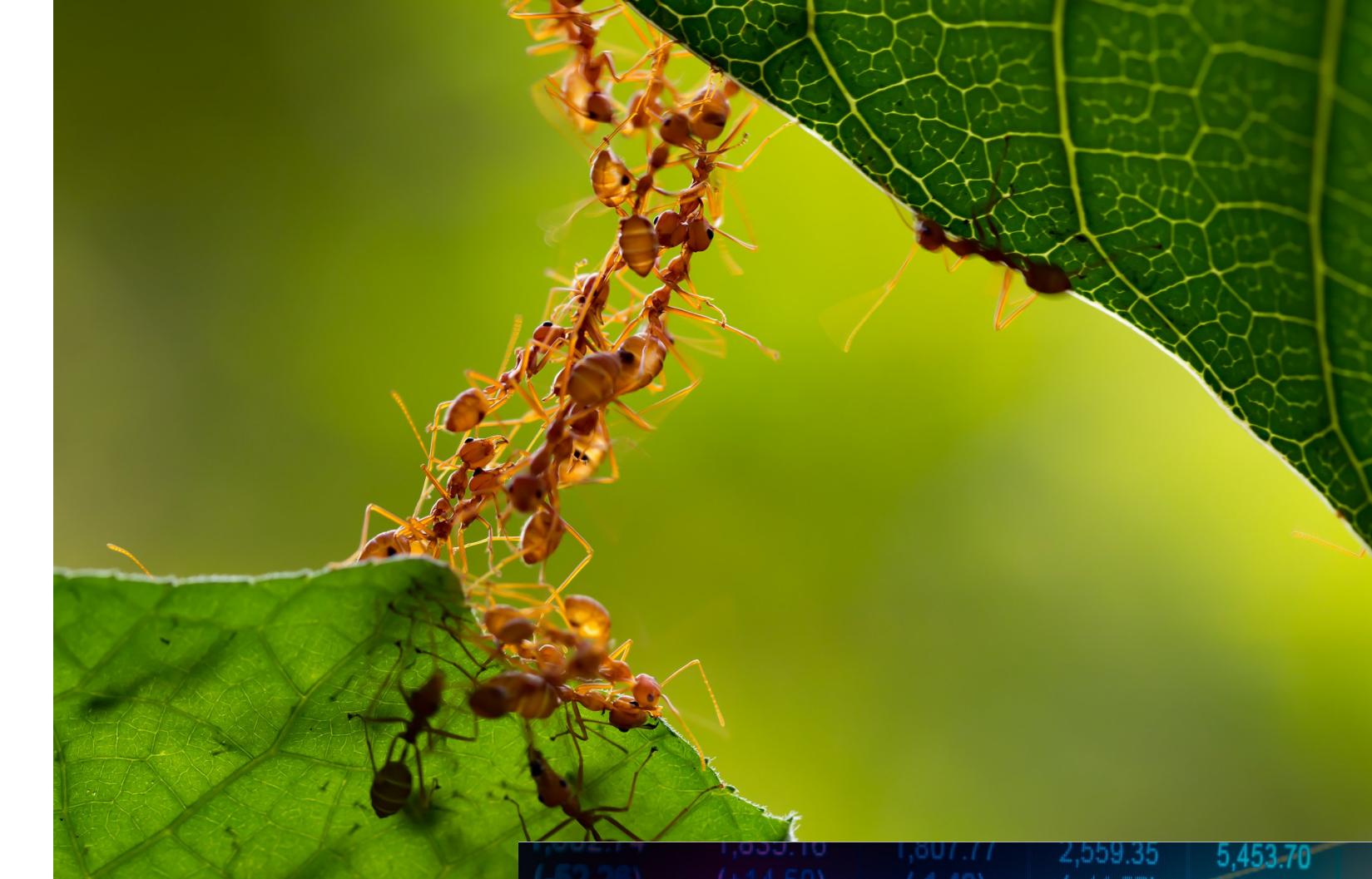


**Q1:** How do individuals that act on their own create beautiful emerging patterns?

.....

**Q2:** How do those patterns of behavior then feed back to affect those individuals?

# Some Applications

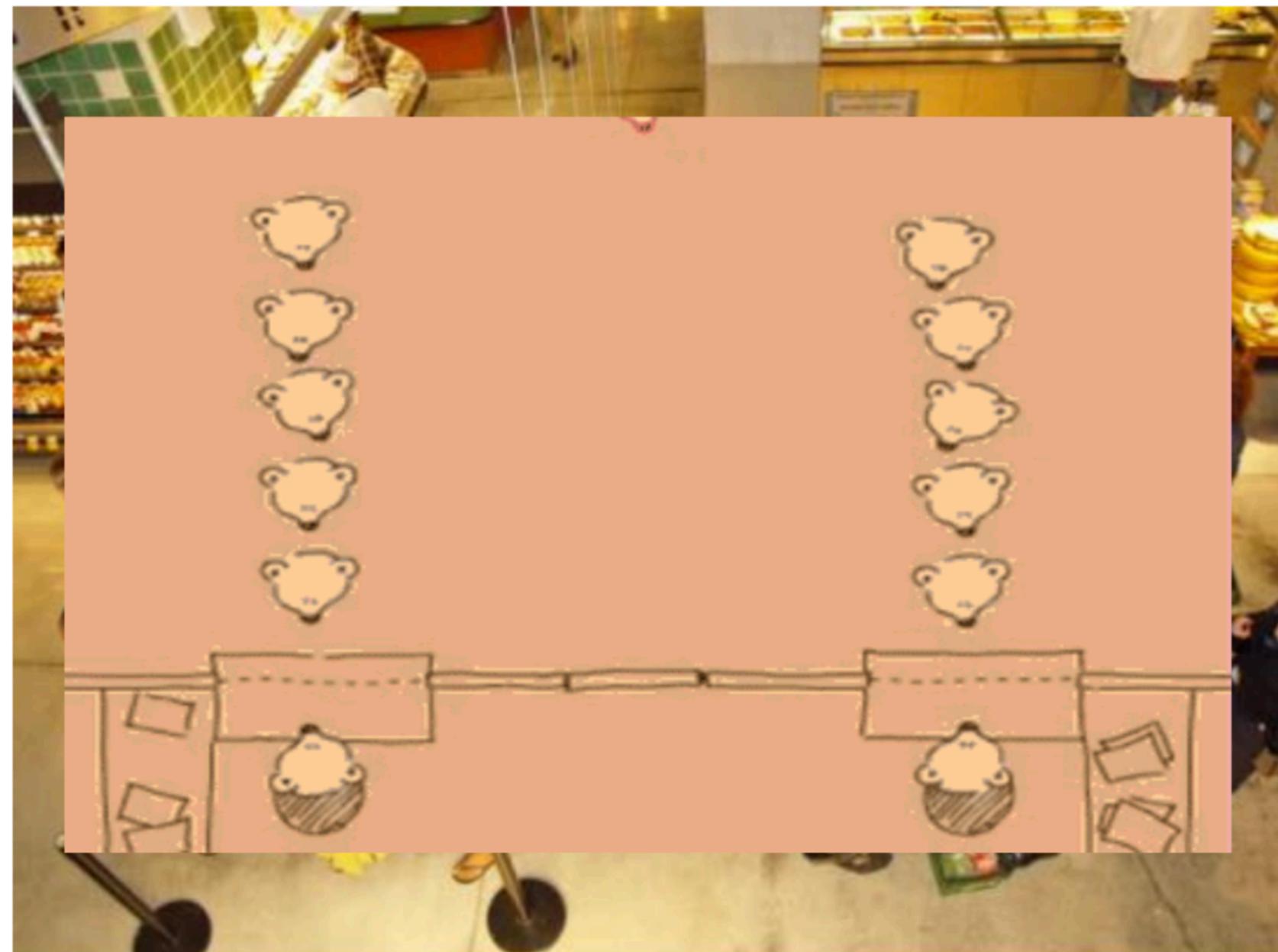


# Which Queue to Choose?

Real world

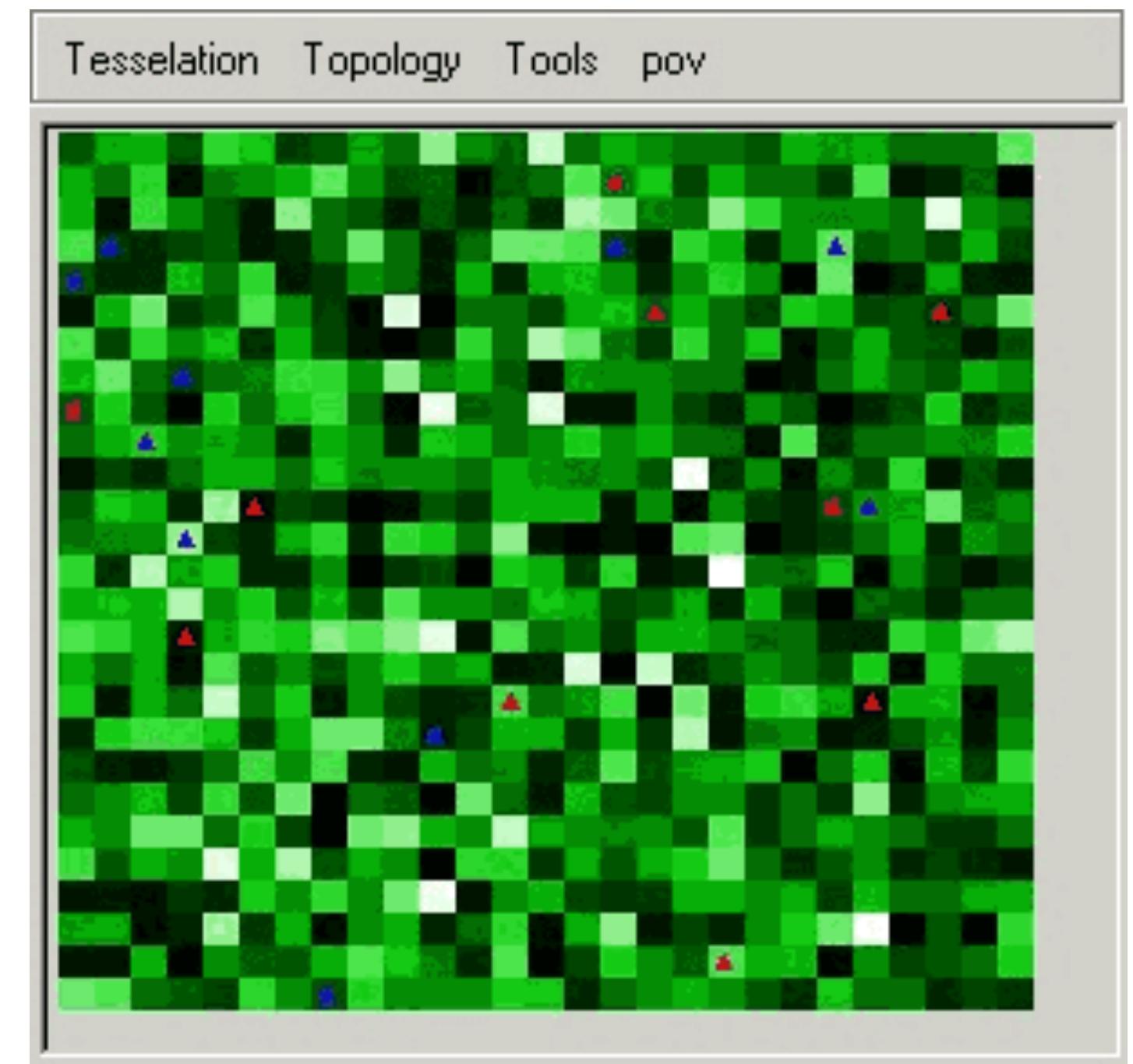
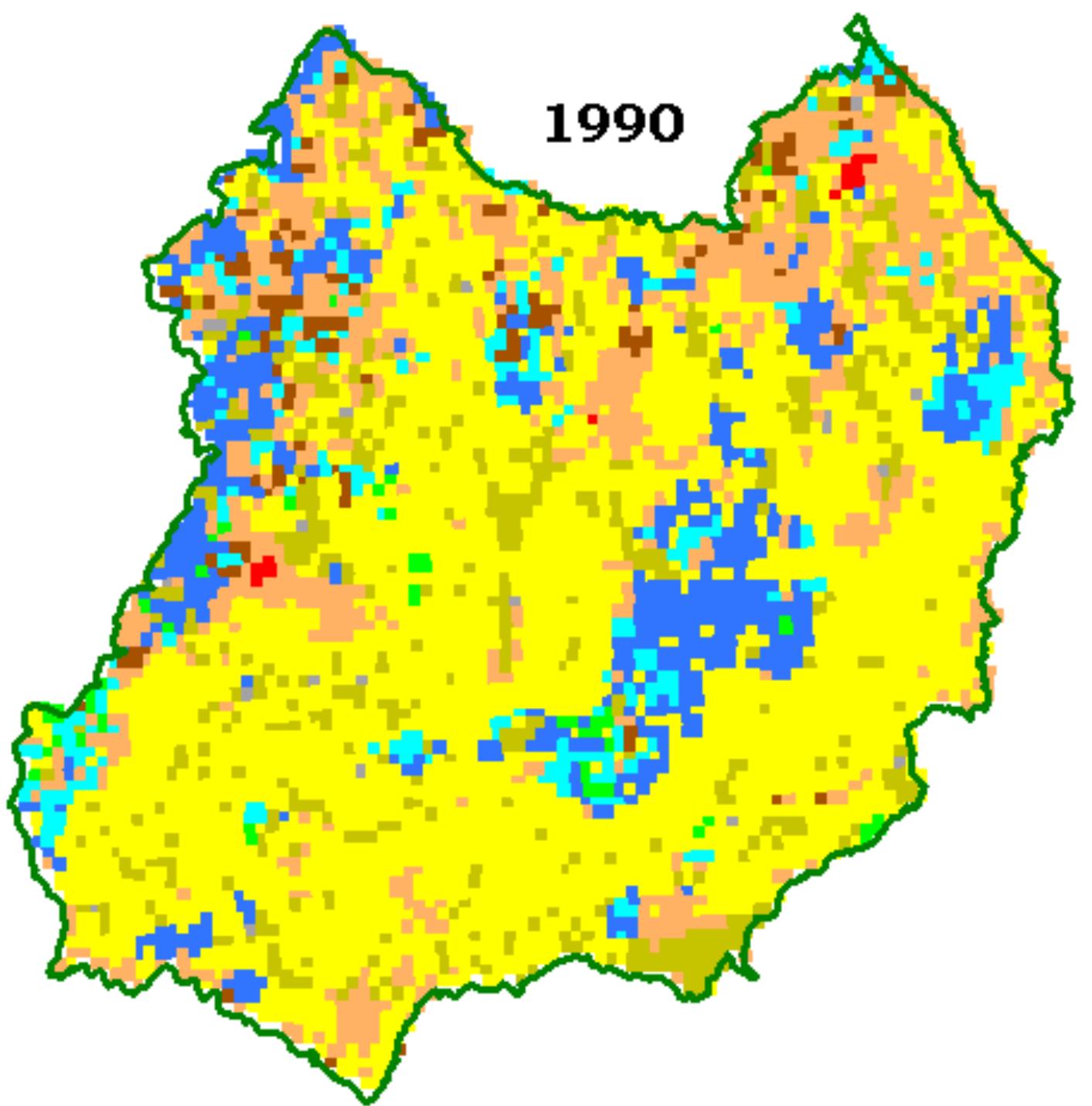
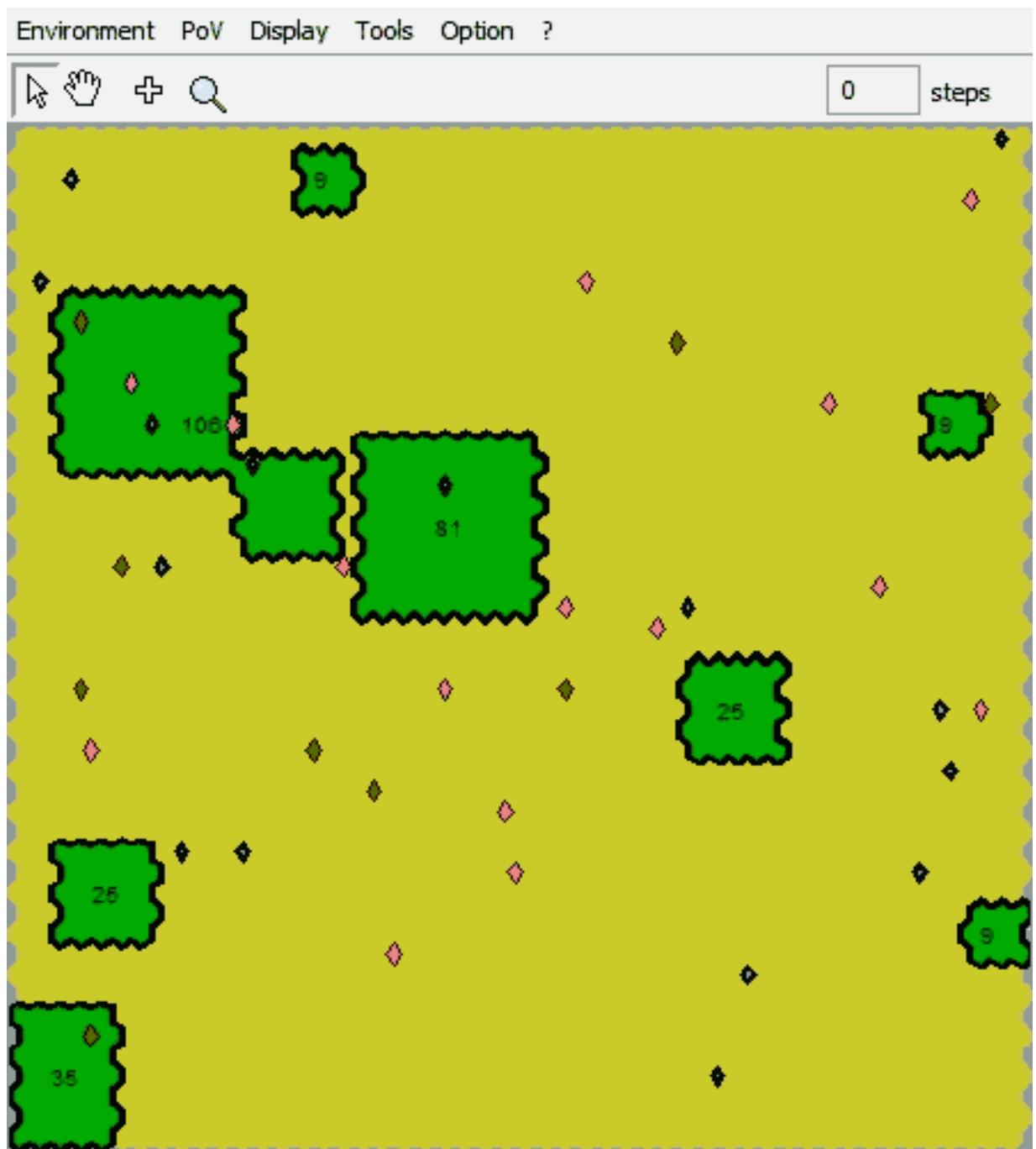


Model



# Your Own Little Lab

*Test theories, explore interactions ...*



# ABM Platforms



The image displays three side-by-side screenshots of Agent-Based Modeling (ABM) platforms:

- NetLogo:** Shows a simulation of ants on a textured surface. A control panel on the left includes sliders for "Number of ants" (200), "Evaporation of the signal (unit/cycle)", and "Rate of diffusion of the signal (%/cycle)". Below the simulation are two plots: "Percent Similar" (y-axis 0-100, x-axis time 0-36.3) and "Number-unhappy" (y-axis 0-454, x-axis time 0-36.3). A command center at the bottom contains the observer and command fields.
- CORMAS:** Features a large green and pink circular logo. Below it, the text "Common pool Resources and Multi-Agent Simulations" is displayed. The interface includes a UML Class Diagram Editor, a simulation control panel with "Initialize", "Forward", and "current step" (1000) and "final step" (1000) buttons, a "CORMAS - Probes - DundiModel (1.0)" window showing line graphs for various metrics like dryGrass, averageV, freshGrass, noGrassF, and numberC over time, and a "CORMAS - Space Interf" window showing a spatial map with colored cells representing different resource types.
- Pharo:** Shows a GAML reference search bar and a navigation menu with links to Pharo, I18N Translations, CORMAS, Browse, UML Class Diagram Editor, Debug, Sources, System, Library, Windows, Help, Roassal, OpenPonk, and OntoUML UFO-A Editor. It also includes a "CORMAS - DundiModel (1.0)" window with simulation controls and a "CORMAS - Probes - DundiModel (1.0)" window showing probe data.

The background of the slide is a vibrant aerial photograph of a rural area featuring numerous terraced rice fields. The fields are arranged in a grid-like pattern, following the contours of the land. The colors range from deep green to bright yellow, indicating different stages of rice growth or different varieties. Small clusters of traditional houses with thatched roofs are scattered throughout the fields. A few small roads and streams are visible. The overall scene is a lush, agricultural landscape.

## Part 2: Cormas Platform

# Cormas Platform



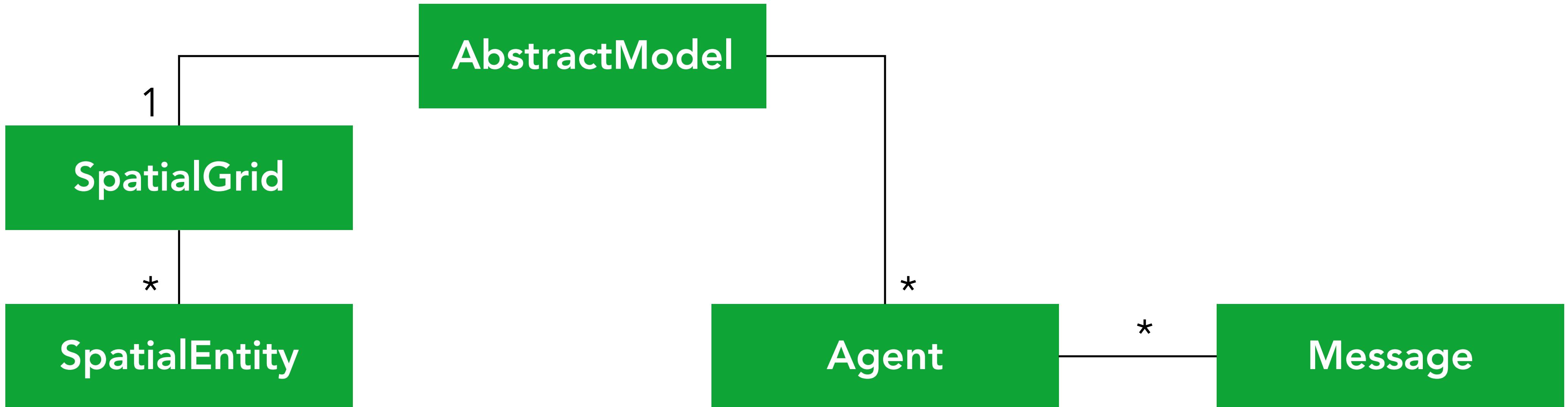
Common pool Resources  
and Multi-Agent Simulations

- ✓ Multi-agent simulations
- ✓ Developed in 90s by Green Unit
- ✓ Originally implemented in VisualWorks
- ✓ Ongoing migration to Pharo

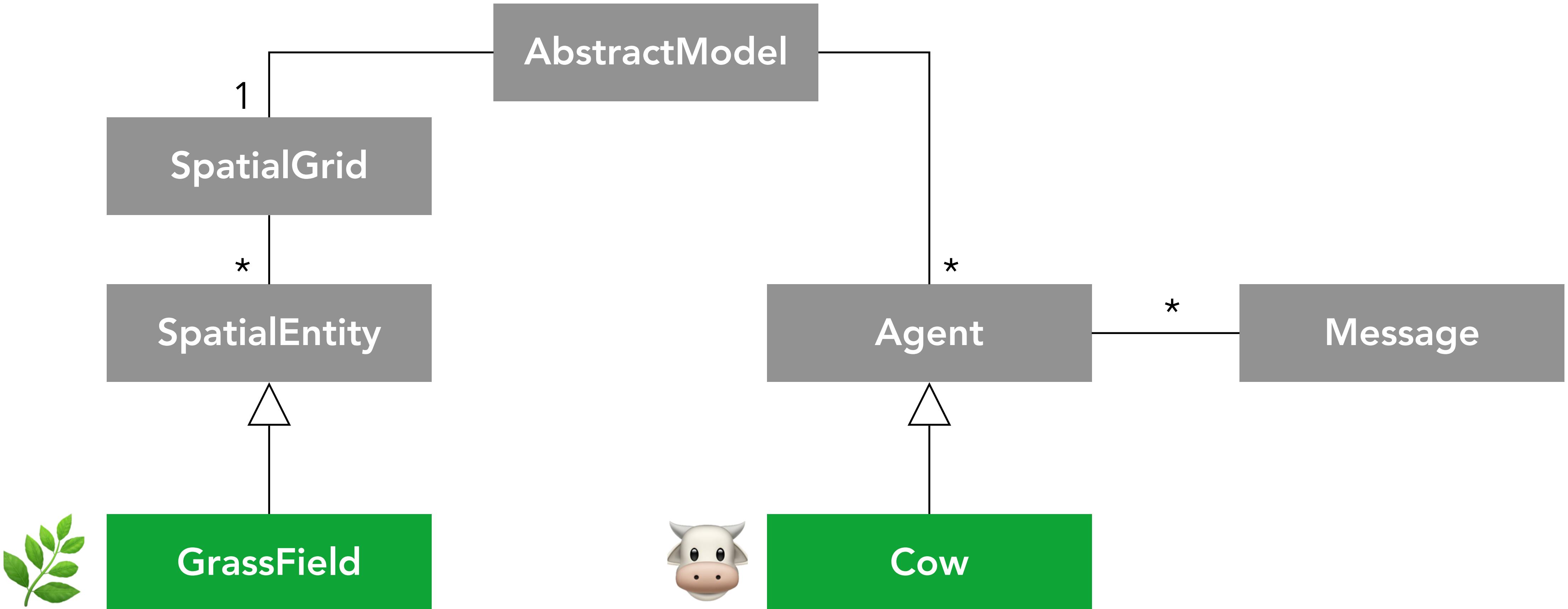
The screenshot displays three main components:

- Issue Tracker:** A Jira-style interface titled "Cormas Development" showing a list of open issues. The issues are categorized by priority: Priority 2 (Emergency) and Priority 3 (Urgent). Each issue includes a title, assignee, status, and labels. One issue is labeled "Bug".
- Book Cover:** A book titled "Cormas : Building Agent Simulations With Pharo" by Etienne Delay, Pierre Bommel, Bruno Bonté, Nicolas B... (partially visible). The cover features a colorful abstract design.
- Table of Contents:** An open book showing the table of contents for the book. The contents include chapters on modeling, building models from scratch, beyond basics, analysis, and experiments. Each chapter has a page number next to it.

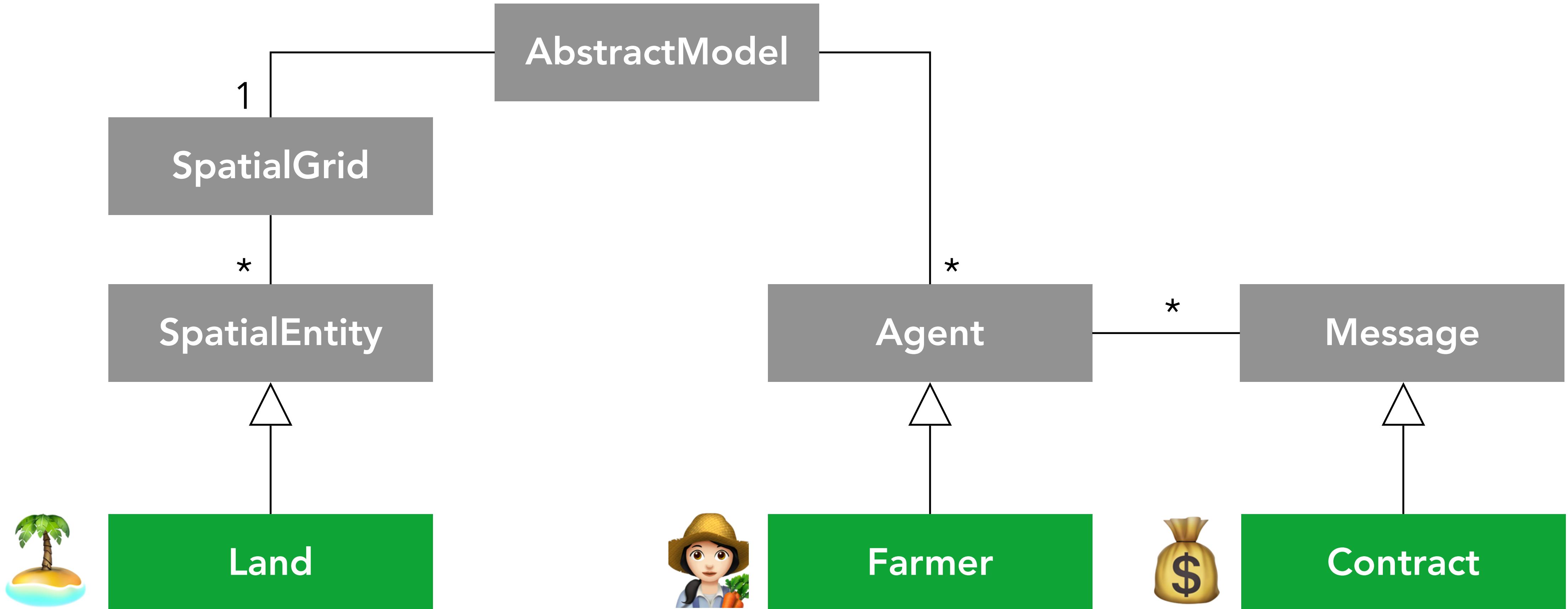
# Basic Classes



# Located Agents



# Communicating Agents



# What Makes Cormas Unique?



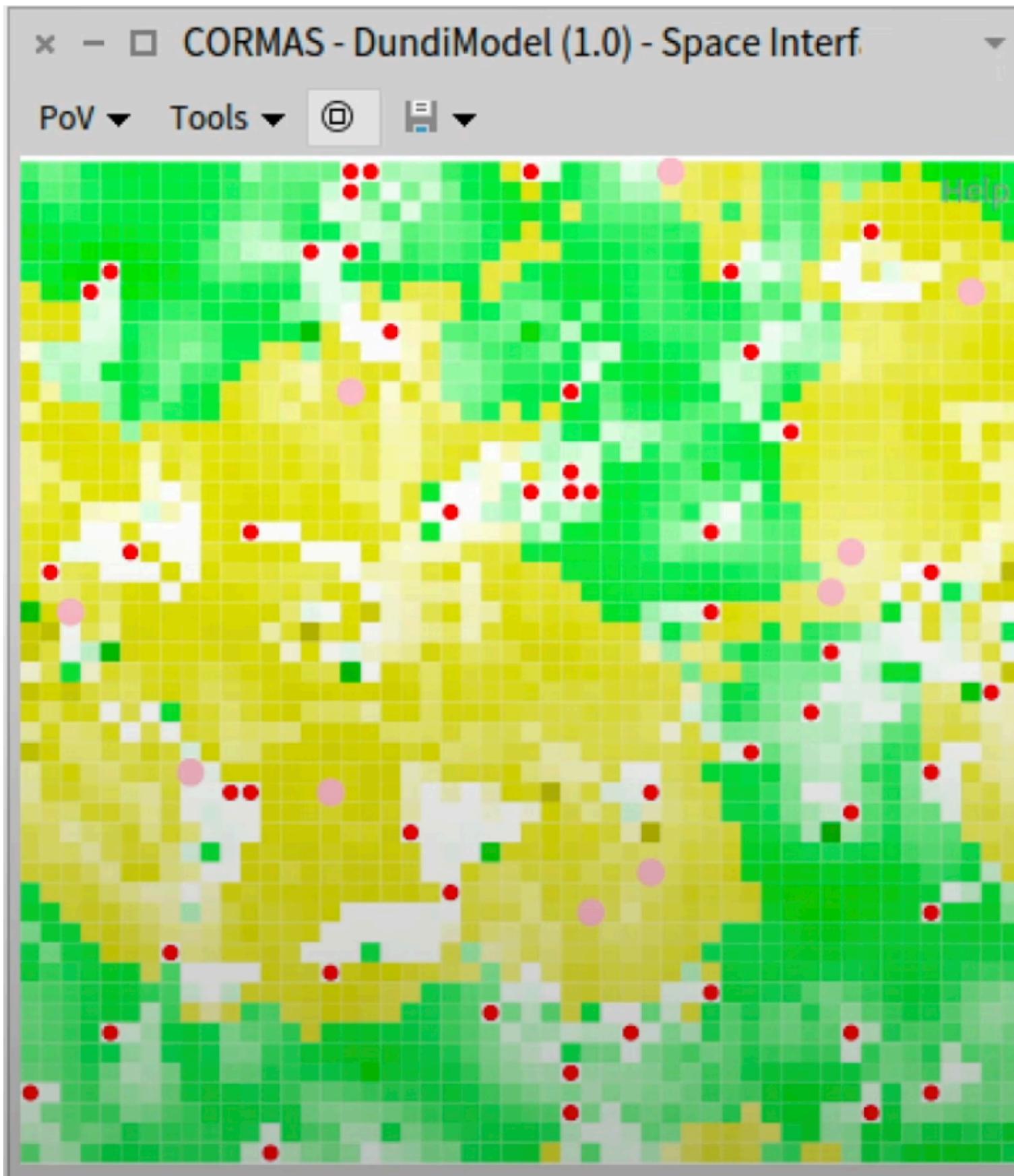
Cormas is **interactive** and particularly well adapted for the **participatory** modelling.

It provides different « points of view », allows users to inspect and control specific agents, allows stepping back in time.

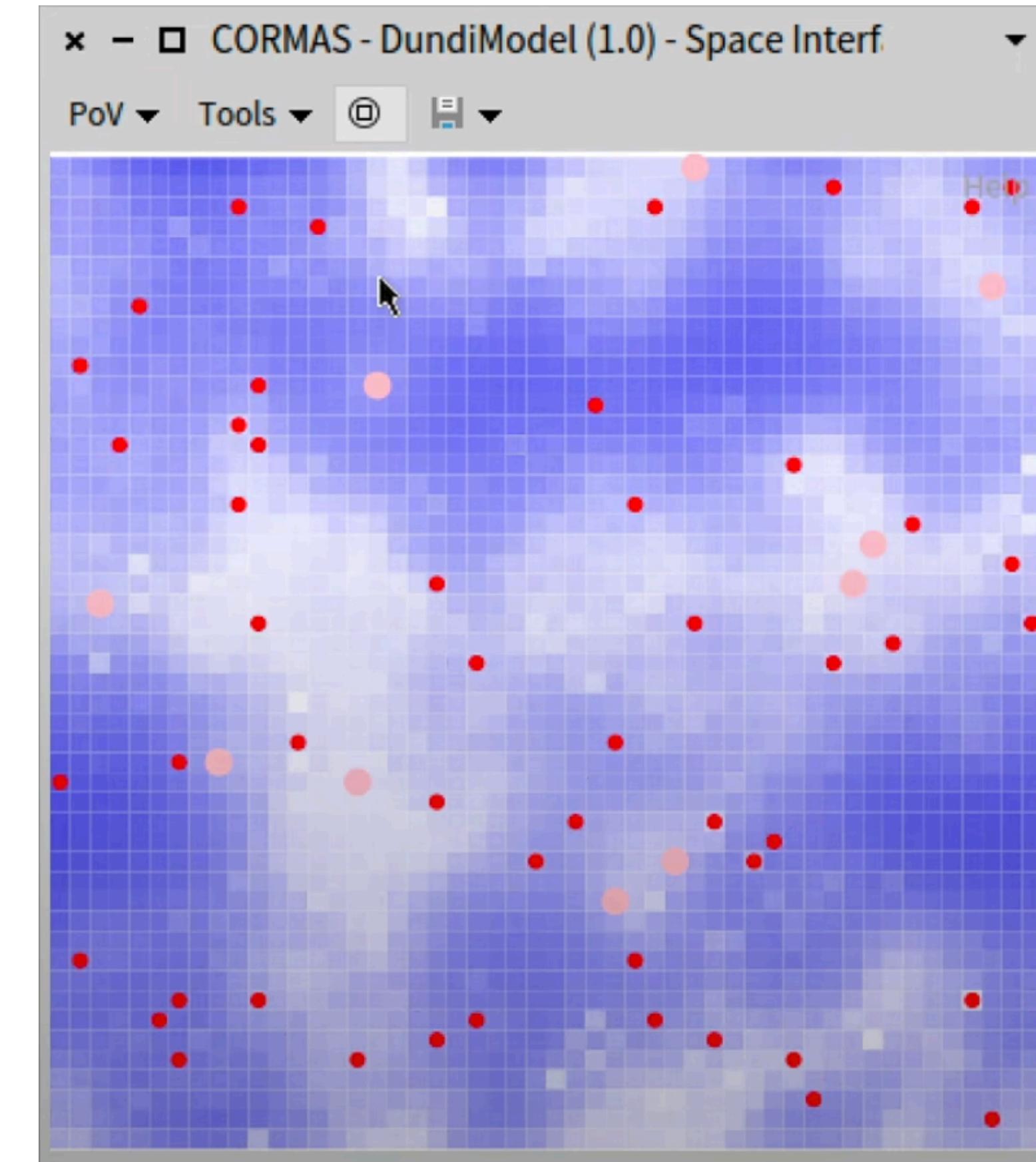
# Different « Points of View »



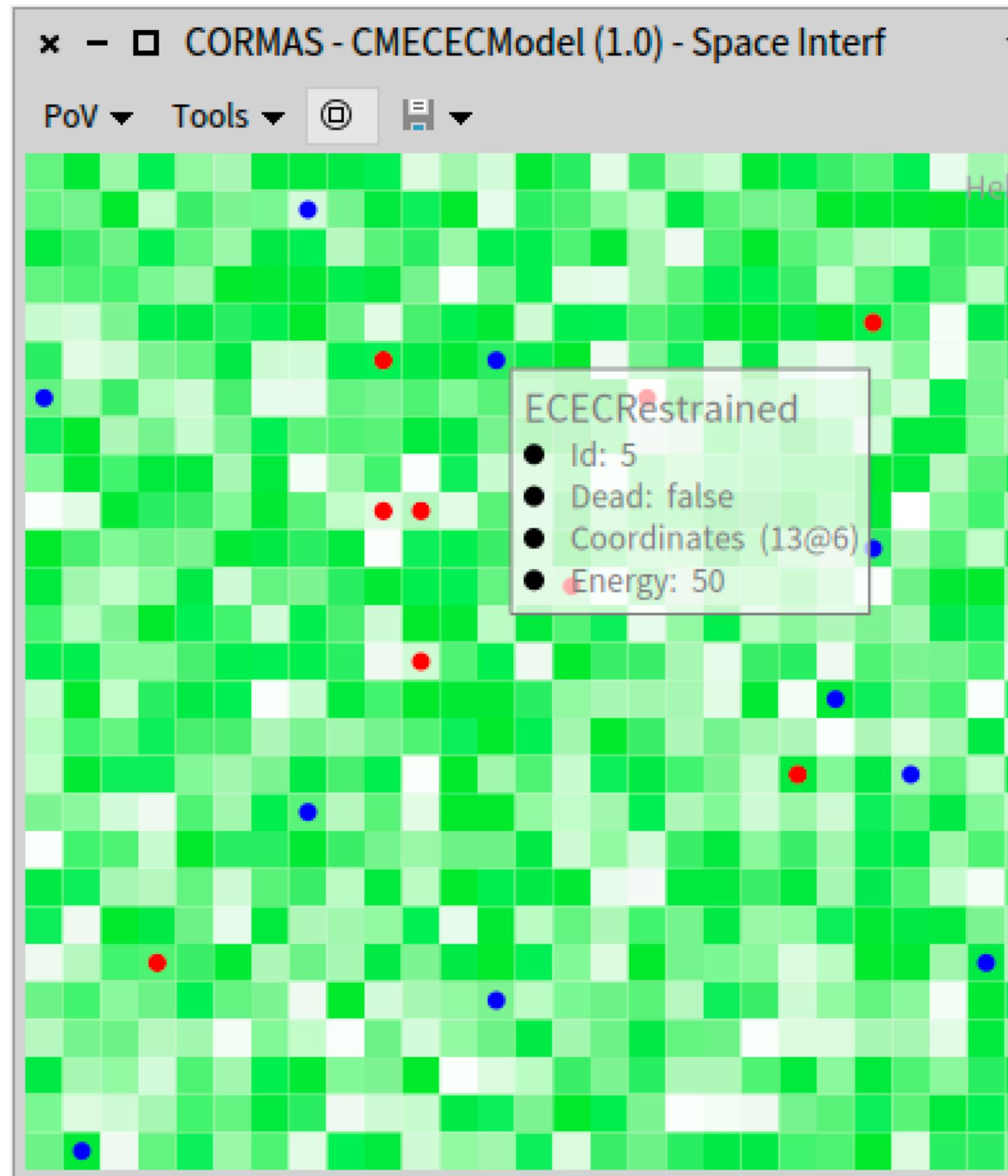
PoV 1: Grass



PoV 2: Water



# Inspect and Control Agents



x - □ Inspector on a CMECECRestrained -id: 5-coord: (13@6)

a CMECECRestrained -id: 5-c...

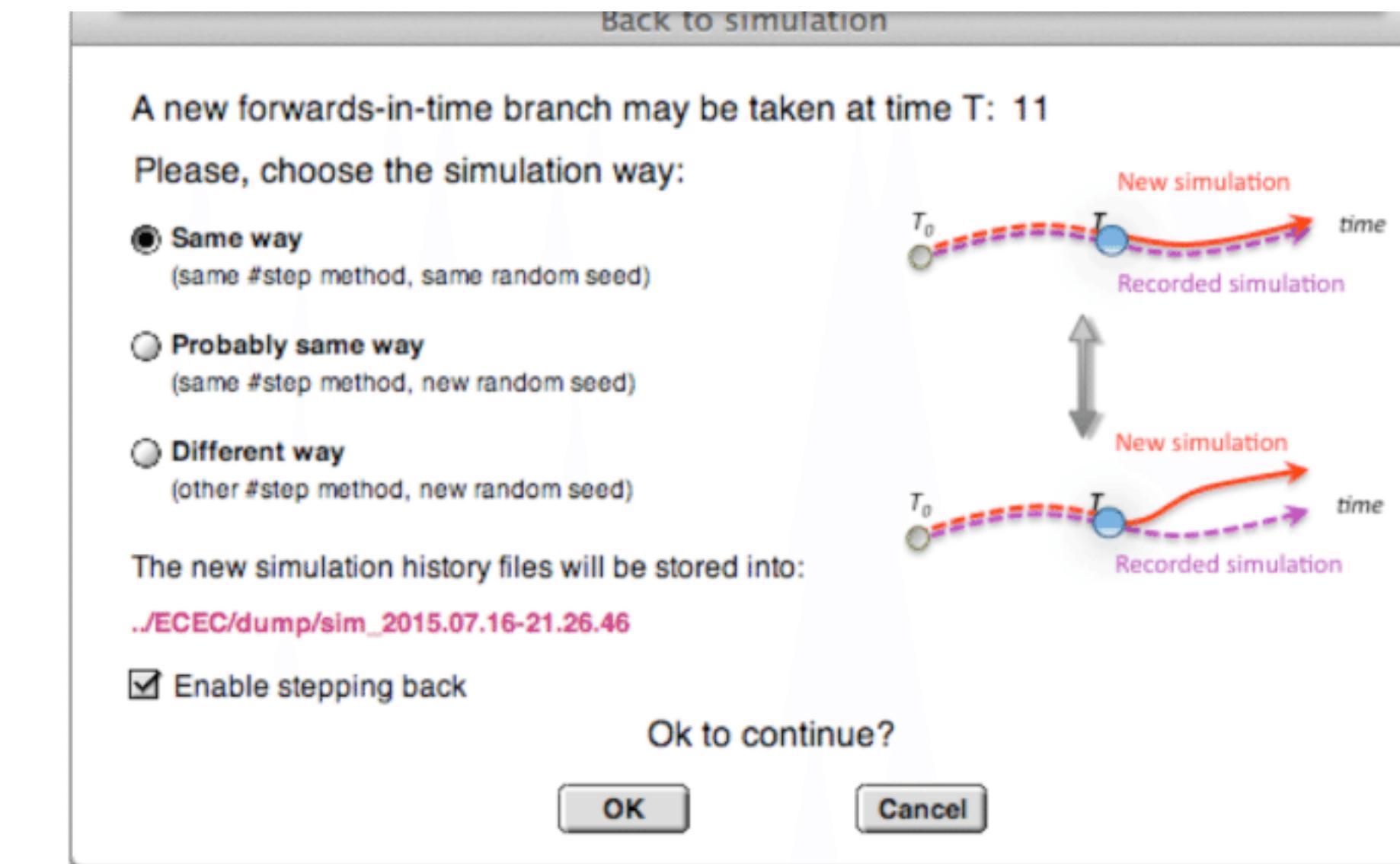
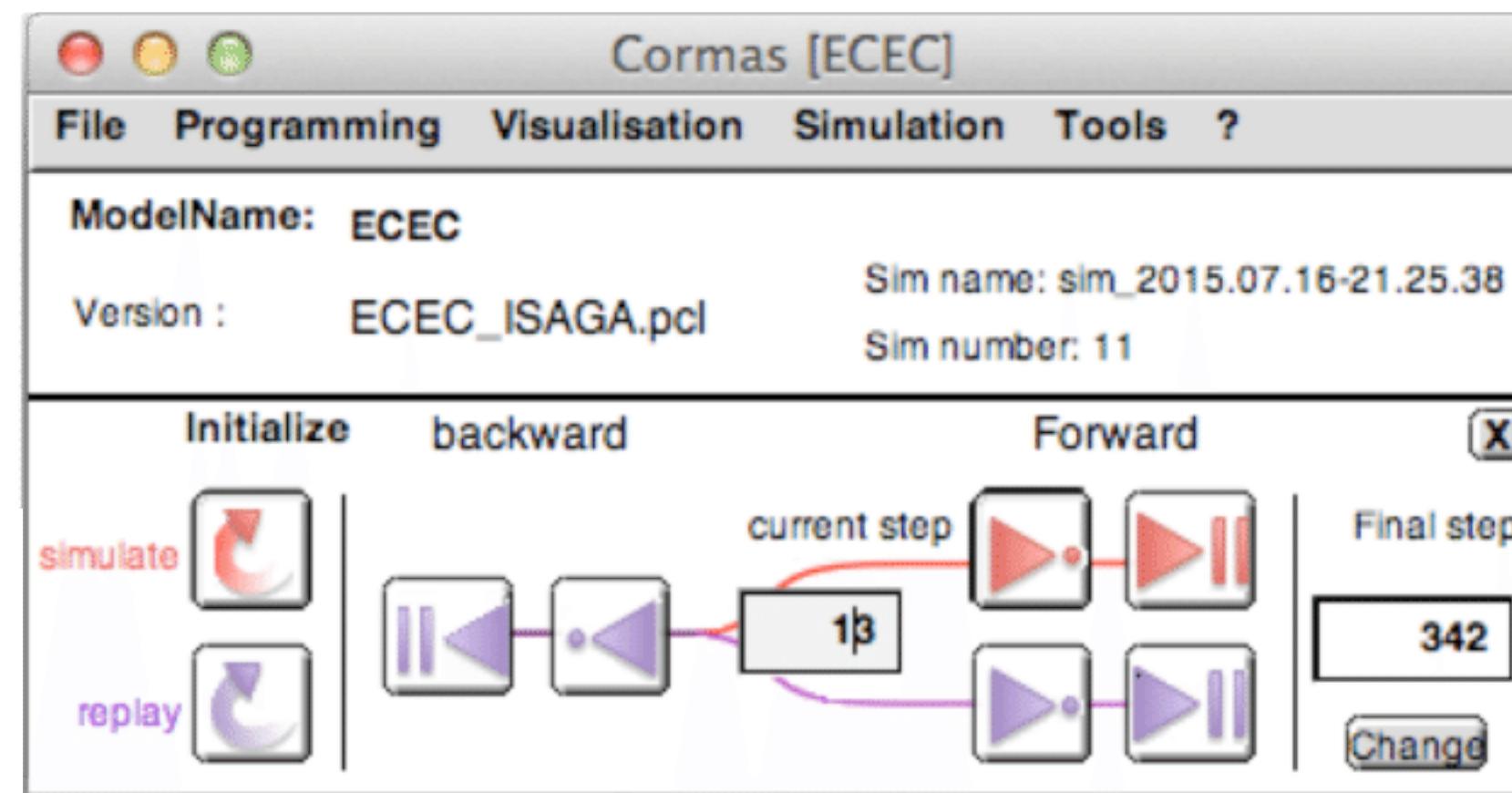
Raw	Breakpoints	Meta
<b>Variable</b>	<b>Value</b>	
↳ self	a CMECECRestrained -id: 5-coord: (13@6)	
↳ translator	nil	
↳ id	5	
↳ flag	nil	
↳ collector	a CMCollector	
↳ request	nil	
↳ cormasModel	a CMECECModel (init: true, time: 0, entities: 749)	
↳ dead	false	
↳ patch	a CMECECVegetationUnit -id: 148 -n: 8 -o: 1	
↳ energy	50	

```
1 "a CMECECRestrained -id: 5-coord: (13@6)"  
2 self
```

# Stepping Back in Time



Not yet supported in Pharo version

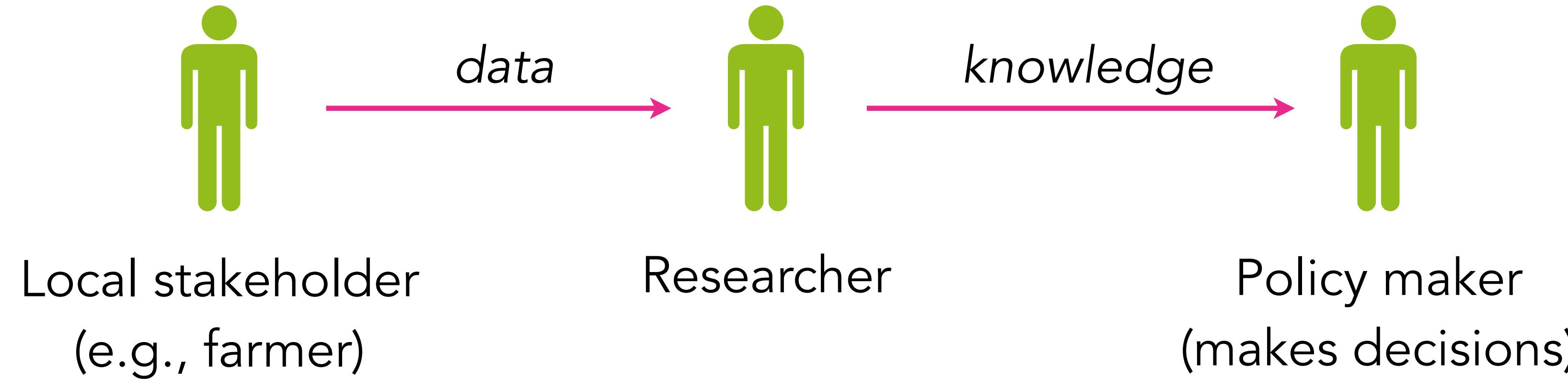




## **Part 3:**

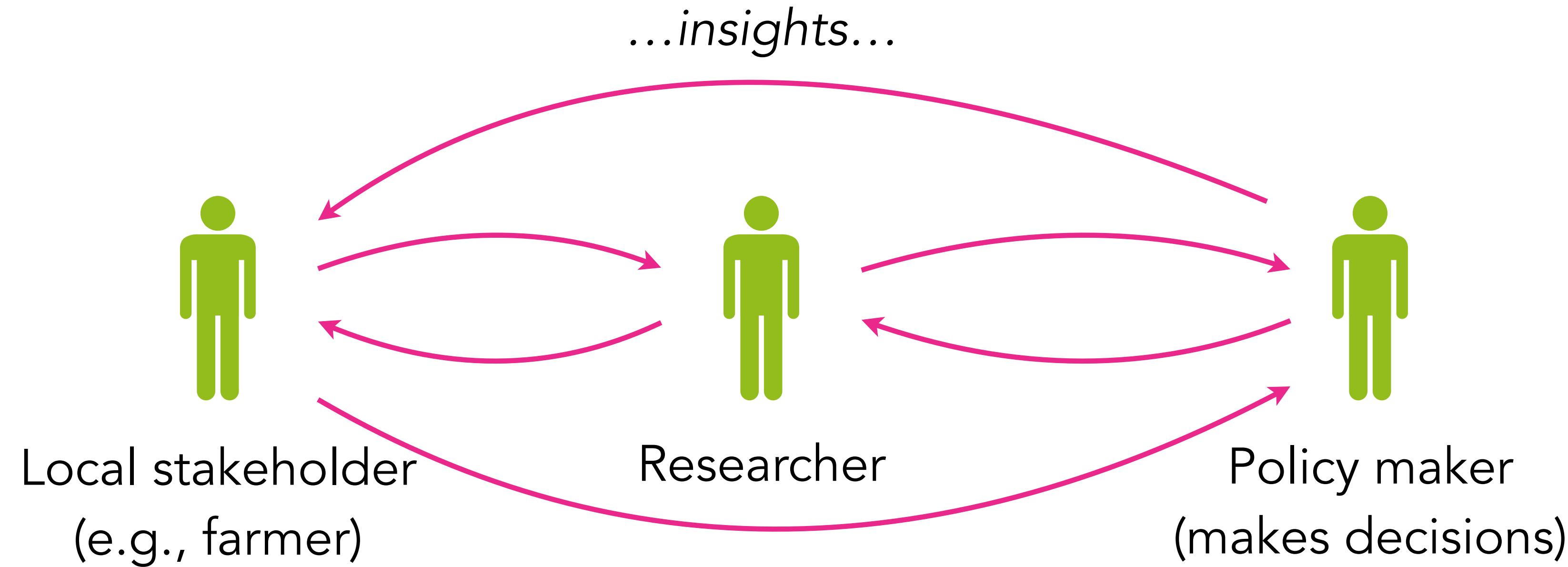
# **Research Directions**

# « Conventional » Modelling



Local stakeholders are only contacted for data collection

# Participatory Modelling

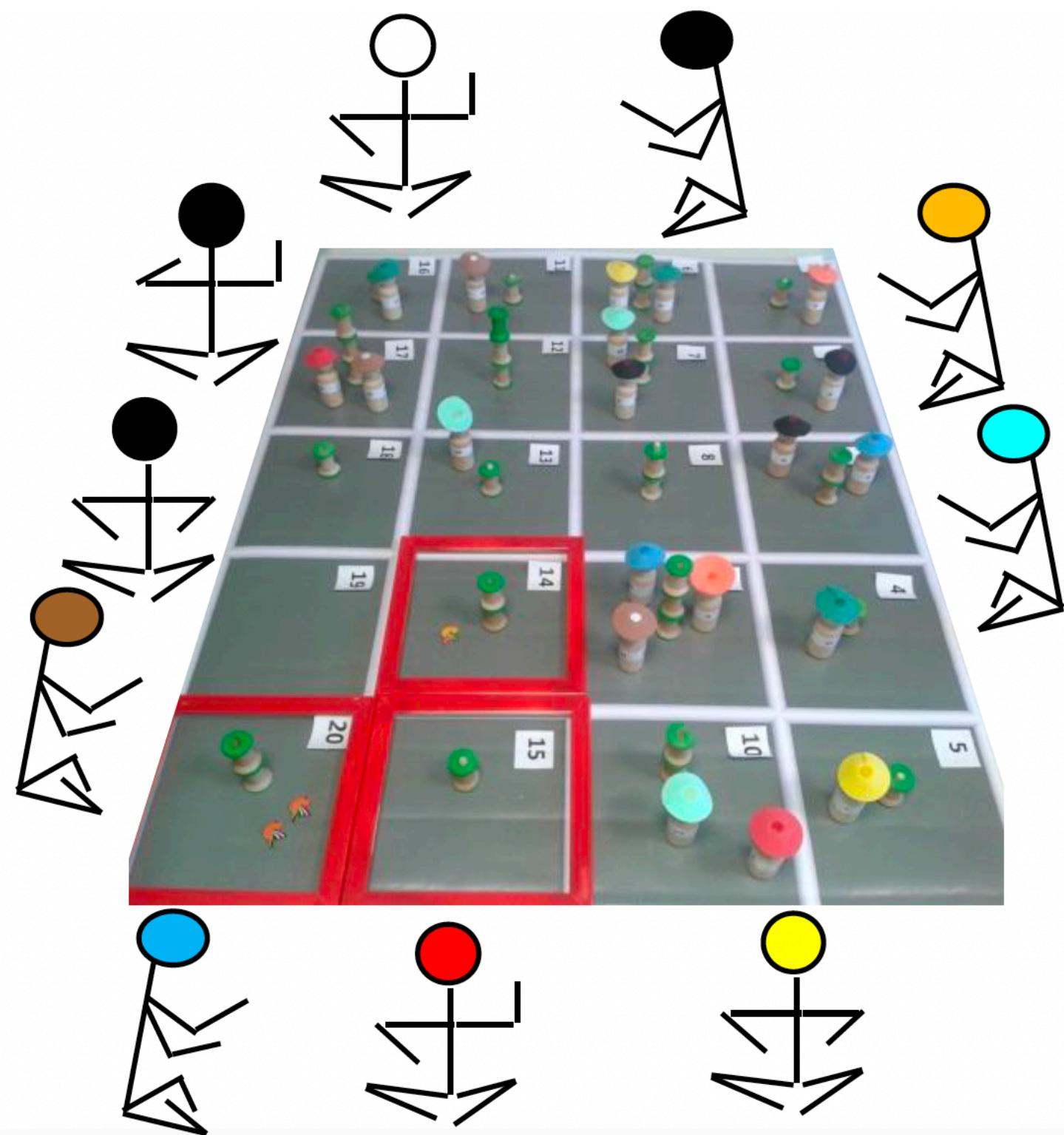


Local stakeholders are involved in every step of modelling: data collection, model building, model exploration

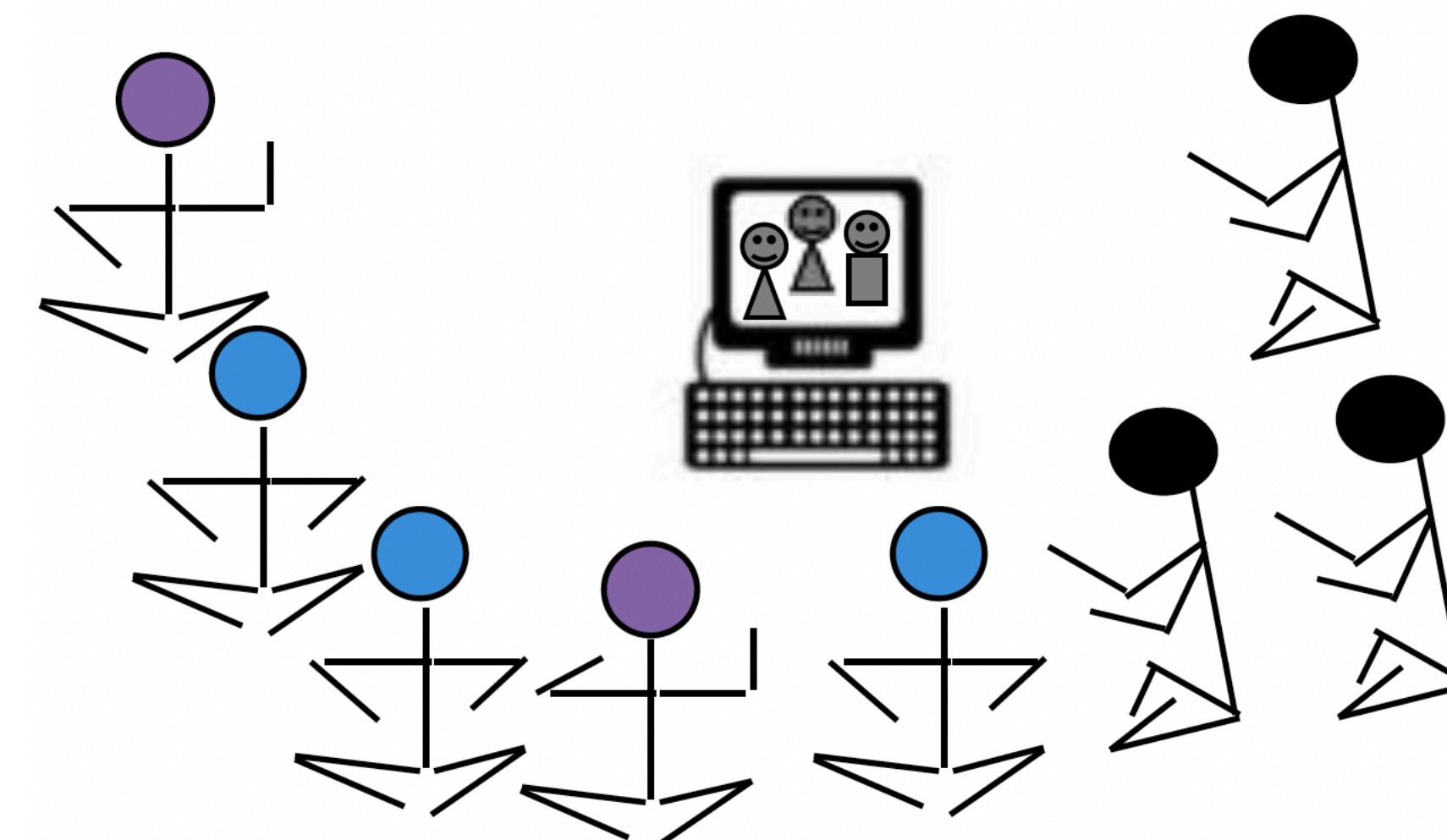
# Our Two Activities at CIRAD



## Role-Playing Games



## Agent-Based Modelling



# Role-Playing Games (no computers)



## Pros:

- Accessible
- Personal
- Interactive

## Cons:

- Slow
- Imprecise
- Analysed later

# Agent-Based Modelling



## Pros:

- Fast & Powerful
- Immediate analysis (statistical, visual)

## Cons:

- Unaccessible (too technical)
- Impersonal (barrier between researcher and participants)

# Hybrid Approach



Combine the  
benefits of both

- People have real (tangible) interactions
- Computer observes and supports them

# Computerization



## One way to do it:

Use software, AI, and IoT to replace humans in cumbersome tasks

## Another way:

Empower citizens to be the actors of their own social transformation.

Use software, AI, and IoT to build tools for effective communication, exploration, and knowledge sharing

# Three Research Directions



## Topic 1: Modelling Language

*What is the language that would allow non-programmers to define models easily?*

## Topic 2: Tangible Interaction

*Can we help stakeholders to build and control models through physical interaction?*

## Topic 3: Collaborative Modelling

*Can multiple people interact with the same model simultaneously with different PoV?*

# Topic 1: Modelling Language



*What is the language that would allow non-programmers to define models easily?*

## Problem:

Modelling involves programming.

Programming is difficult for non-programmers

*How hard would it be for geographer  
or biologist to use an ABM platform  
for the first time?*

Can we make it easier?

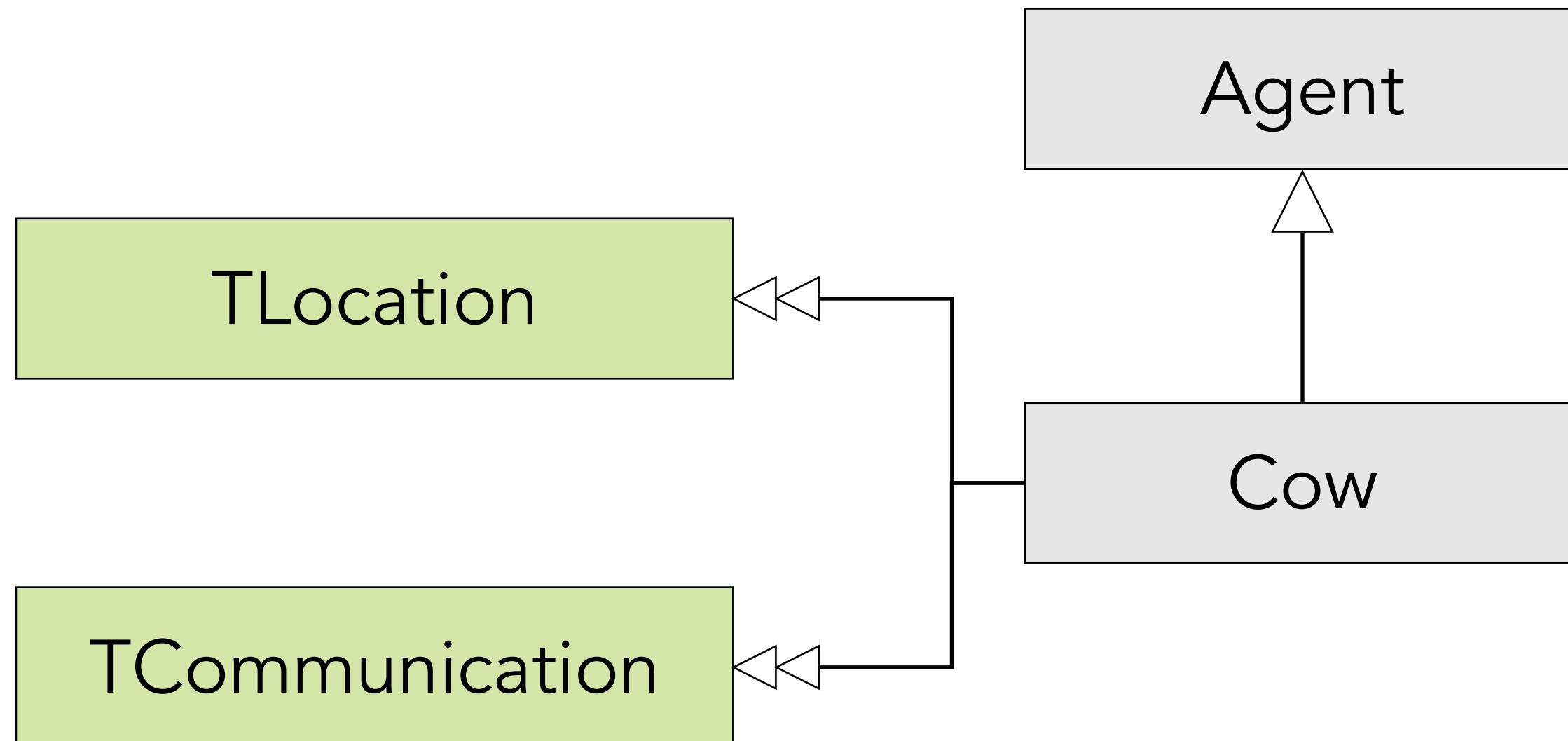
More intuitive?

The screenshot shows the NetLogo interface with a tab titled "NetLogo — Fire". The code editor displays the following NetLogo script:

```
globals [  
    initial-trees ;; how many trees (green patches) we started with  
    burned-trees ;; how many have burned so far  
]  
  
breed [fires fire] ;; bright red turtles -- the leading edge of the fire  
breed [embers ember] ;; turtles gradually fading from red to near black  
  
to setup  
    clear-all  
    set-default-shape turtles "square"  
    ;; make some green trees  
    ask patches with [(random-float 100) < density]  
        [ set pcolor green ]  
    ;; make a column of burning trees  
    ask patches with [pxcor = min-pxcor]  
        [ ignite ]  
    ;; set tree counts  
    set initial-trees count patches with [pcolor = green]  
    set burned-trees 0  
    reset-ticks  
end  
  
to go  
    if not any? turtles ;; either fires or embers  
        [ stop ]  
    ask fires  
        | [ ask neighbors4 with [pcolor = green]  
            [ ignite ]  
            set breed embers ]  
        fade-embers  
        tick  
    end  
  
    ;; creates the fire turtles  
    to ignite ;; patch procedure  
        sprout-fires 1  
        [ set color red ]  
        set pcolor black  
        set burned-trees burned-trees + 1  
    end
```

# Topic 1: Modelling Language

*What is the language that would allow non-programmers to define models easily?*



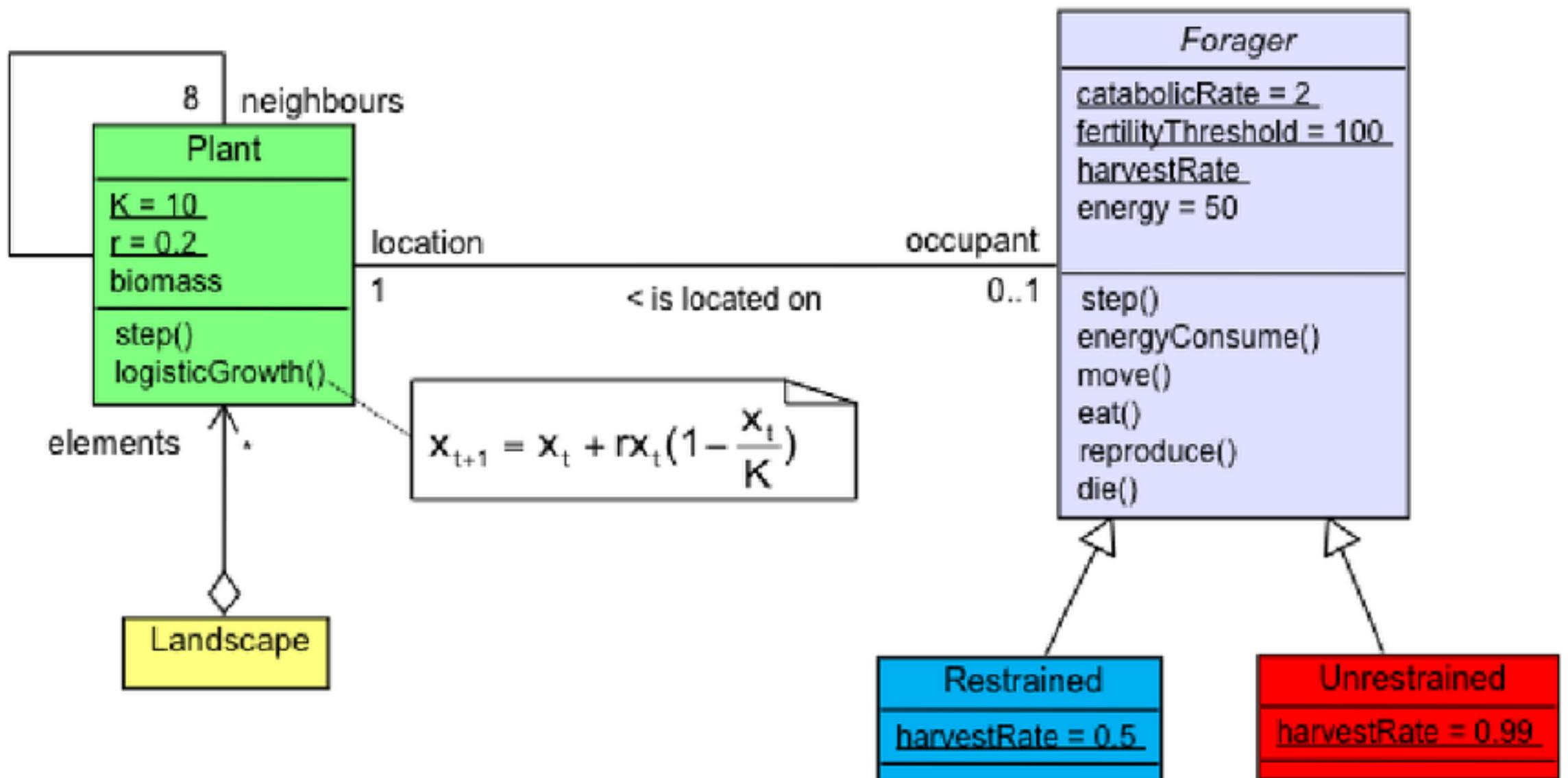
## Solution 1: Object-oriented ABM

- Intuitive OOP framework
- Traits - composable units of behaviour
- Model testing framework

# Topic 1: Modelling Language



What is the language that would allow non-programmers to define models easily?



## Solution 2: Executable diagrams

- ARDI / PARDI diagrams
- UML class diagrams
- UML activity diagrams

# Topic 2: Tangible Interaction

*Can we help stakeholders to build and control models through physical interaction?*

## Problem:

During the participatory sessions in the field, it is often difficult to put every participant in front of a computer and make them manipulate the model.

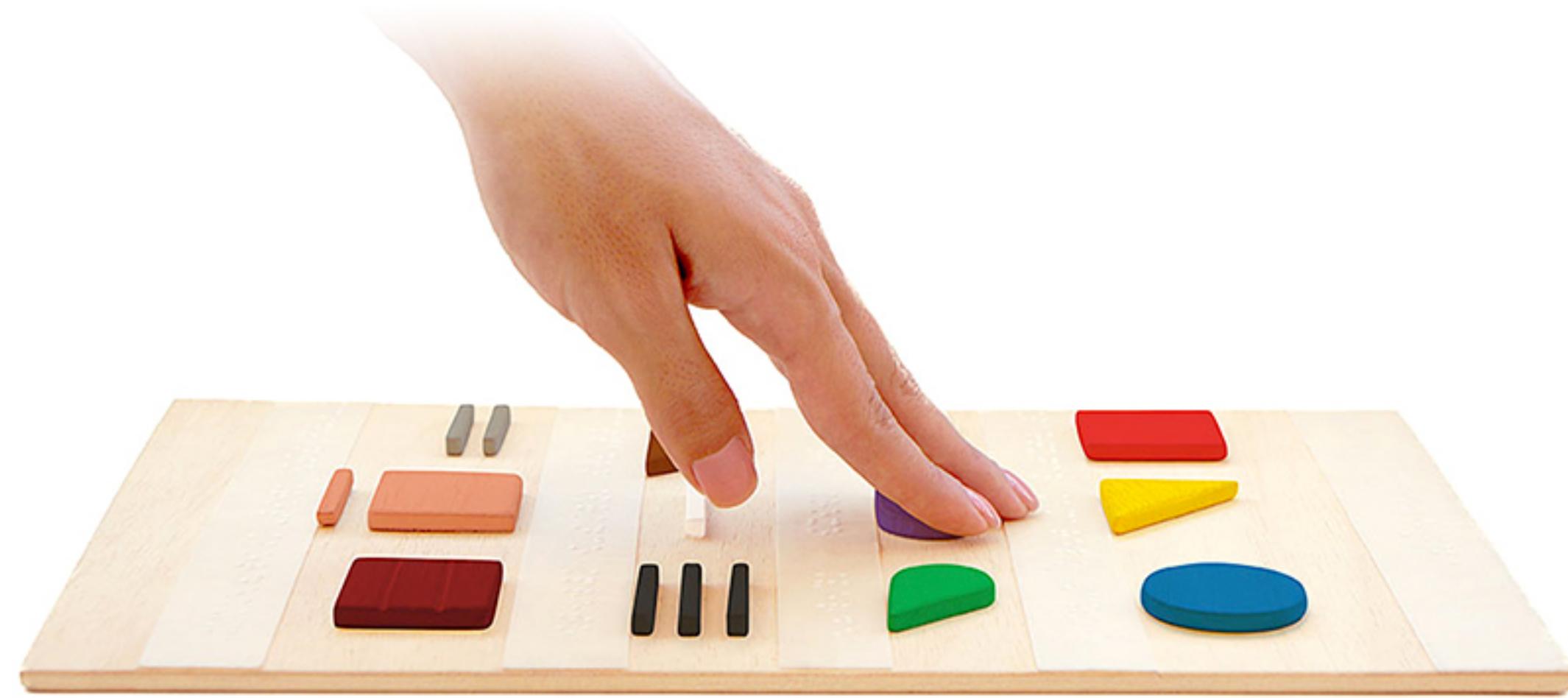
- ⚡ Access to electricity
- 💻 Access to computers
- 📚 Computer literacy



Caroline Dangleant © Cirad

# Topic 2: Tangible Interaction

*Can we help stakeholders to build and control models through physical interaction?*



## Hypothesis:

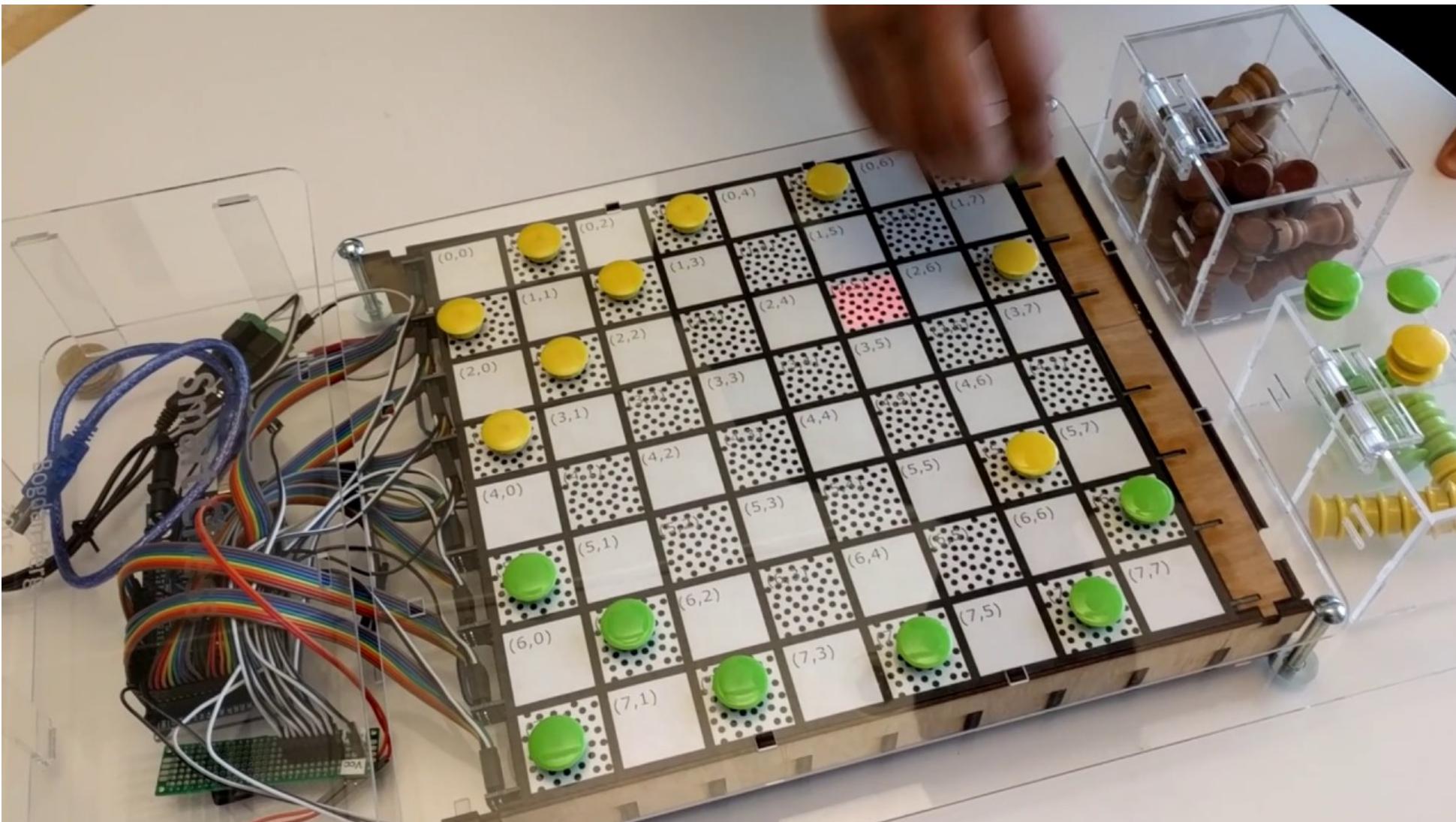
We communicate ideas better when they are tangible.  
Touching something is better than seeing it on a screen

# Topic 2: Tangible Interaction



*Can we help stakeholders to build and control models through physical interaction?*

## Solution 1: Sensory game board



- Game board can detect the position of pieces using sensors
- Implement using Raspberry Pi or Arduino and PharoThings library



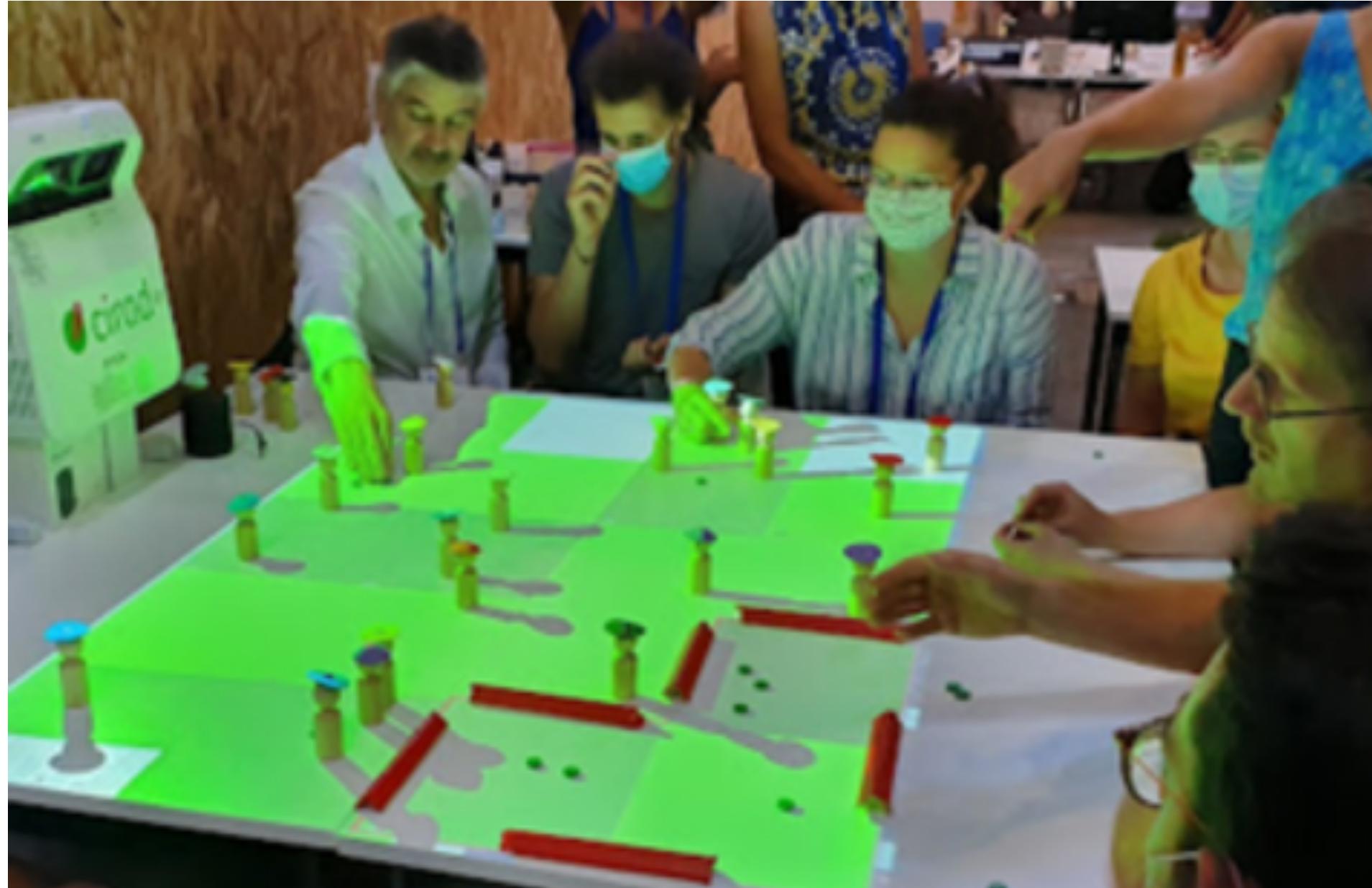
**Mouhamadou Falilou BALL**

Intern at CIRAD  
from UMISSCO, Senegal

# Topic 2: Tangible Interaction



*Can we help stakeholders to build and control models through physical interaction?*



## Solution 2: Computer vision

- AI algorithm that detects game pieces on a table
- Can be paired with simulation projection that was done with Cormas (ReHab?)

Christophe LePage © Cirad

# Topic 2: Tangible Interaction



*Can we help stakeholders to build and control models through physical interaction?*



## Solution 3: Augmented reality

Interactive modelling experience with **virtual reality** (full immersion) or **augmented reality** (enhance real world with computer-generated perceptual information)



# Topic 3: Collaborative Modelling



Can multiple people *interact with the same model simultaneously with different PoV?*

**Problem:** Farmers think about crops, pastoralists think about cows.  
How can we help them understand each other and collaborate?

Farmer



Thierry Brevault © Cirad

Pastoralist



Patrick Dugue © Cirad

Fisherman



Eric Malezieux © Cirad

Policy maker



I. Duriez © Cirad

# Topic 3: Collaborative Modelling



Can multiple people *interact with the same model simultaneously with different PoV?*

**Solution:** One model — many devices.

Different « point of view » and different set of controls  
for each participant



- 🌾 Farmer controls the growth of crops.
- 🐄 Pastoralist manages the behaviour of kettle.
- 🐟 Fisherman observes the amount of fish in the river.
- 💰 Policy maker calculates the expenses.



*... modelling for citizens by citizens*

Modelling environment that is inclusive and takes into account the  
nature of its target communities, adapts to their particular needs  
and helps them overcome their limitations

## Modelling Language

- Object-oriented modelling
- Executable diagrams

## Tangible Interaction

- Sensory game board
- Computer vision
- Augmented reality

## Collaborative Modelling

- One model — many devices
- Multiple « points of view »