Challenges in Debugging Bootstraps of Reflective Kernels

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Why generating custom application runtimes for IoT?



Small Hardware requires software

Limited processing capabilities, storage, battery



Existing approaches: Generating lightweight implementations of Languages from scratch



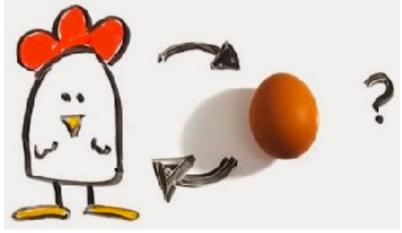
Implement from scratch: VM, base libraries, compiler

Implies complex low level implementation

Requires high expertise to develop!

Our high level approach: Bootstrapping reflective kernels

 Bootstrapping is to generate a system using a previous version of the system that is being generated

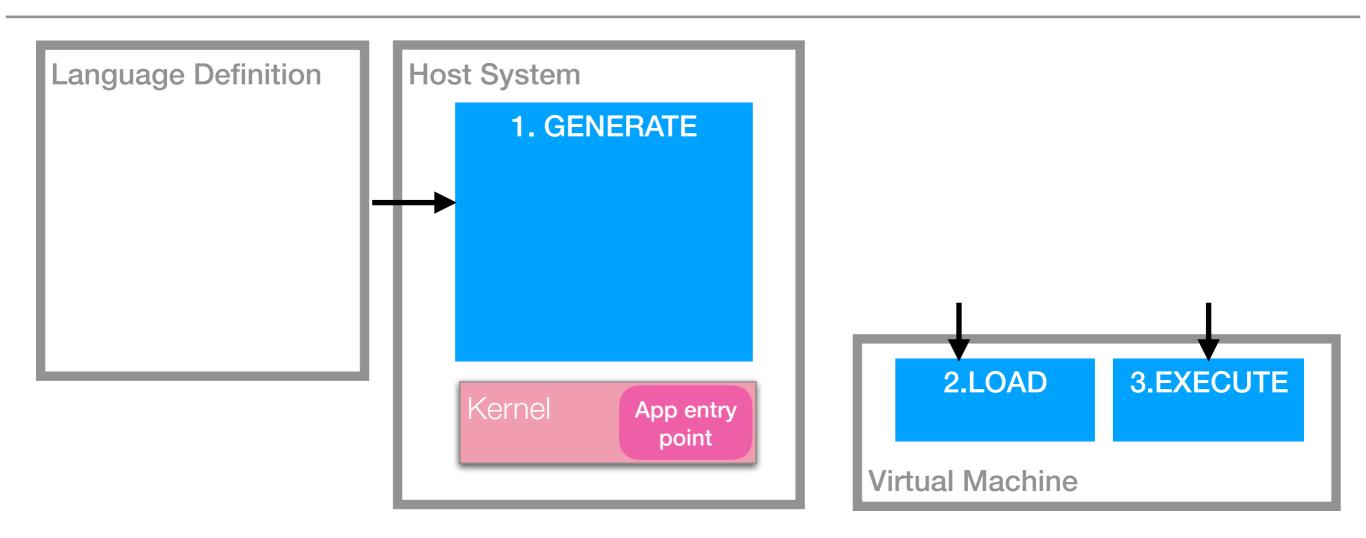


 Therefore we can use the high level abstractions and the reflective capabilities of both systems during the bootstrap

• The result is a **small Kernel** (an image in the case of Pharo) which can be executed by the same VM that executes its previous version

Demo Let's Bootstrap PharoCandle (a Pharo micro kernel)

Bootstrap

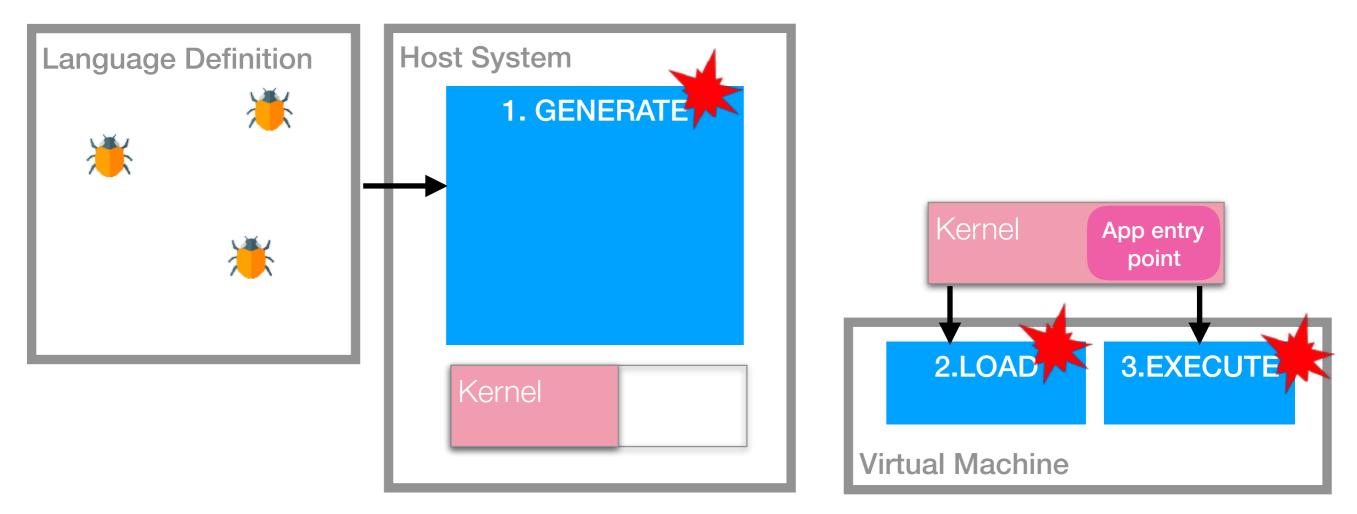


Defects and Failures

Defects & Failures

Content of the second s

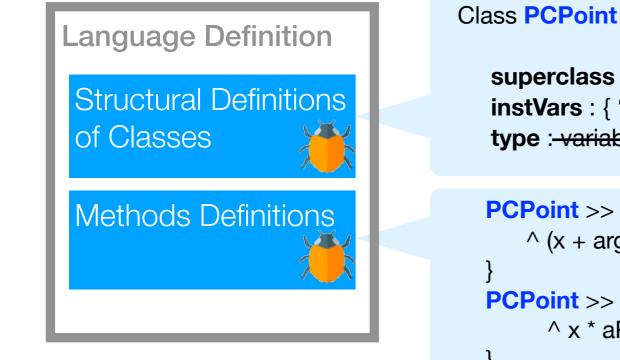
Failure: incorrect result during the Bootstrap



Defects Classification



. . .



superclass : PCObject, **instVars** : { 'x', 'y' }, type :- variable- fixed

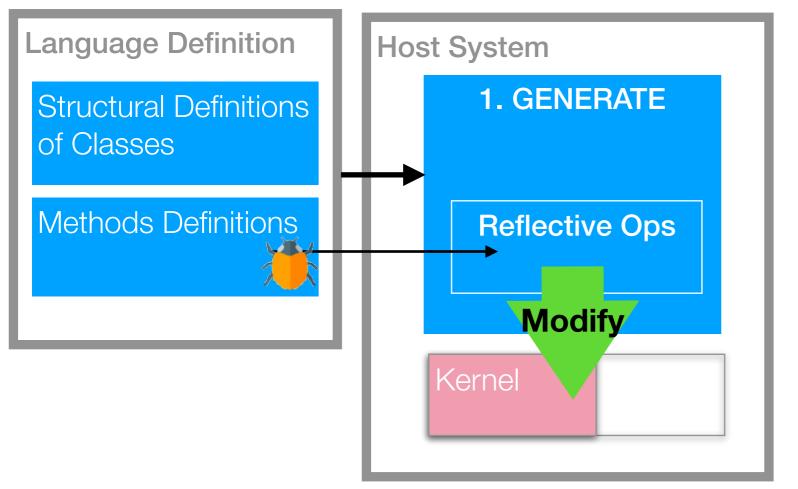
```
PCPoint >> + arg {
   ^{(x + arg x)} @ (y + arg y)
PCPoint >> crossProduct: aPoint {
      ^x * aPoint y - (y * aPoint x)
```

Structural Defect

Semantic Defect

Semantic Defects are Dangerous





Semantic Defects in reflective methods modify the structural definitions in the Kernel

PCClassBuilder >> installMethod: aCompiledMethod inClass: aClass {

aClass methodDictionary add: aCompiledMethod

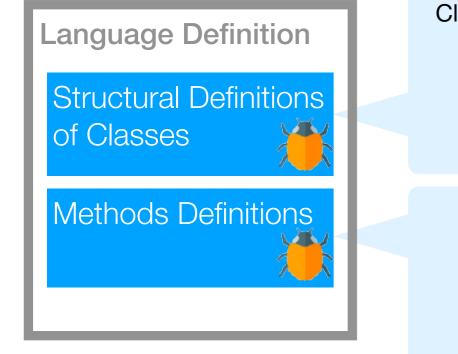
}

The why of defects



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. . .



Class **PCPoint**

superclass : PCObject, instVars : { 'x', 'y' }, type :-variable- fixed

```
PCPoint >> + arg {
     ^ (x + arg x) @ (y + arg y)
}
PCPoint >> crossProduct: aPoint {
     ^ x * aPoint y - (+* aPoint x)
}
```

Structural Defect

Semantic Defect

The why of Defects

Virtual Machine requirements

Kernel 2.LOAD

Segmentation Fault

Class **PCArray**

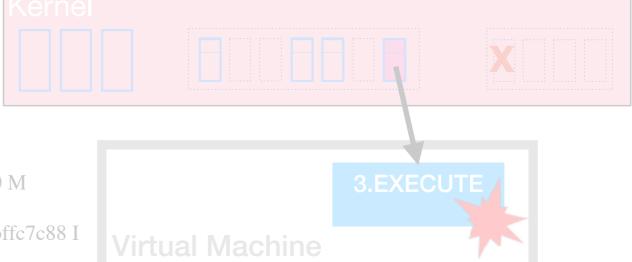
instVars : { },

Type : variable

Application requirements

superclass : PCObject,





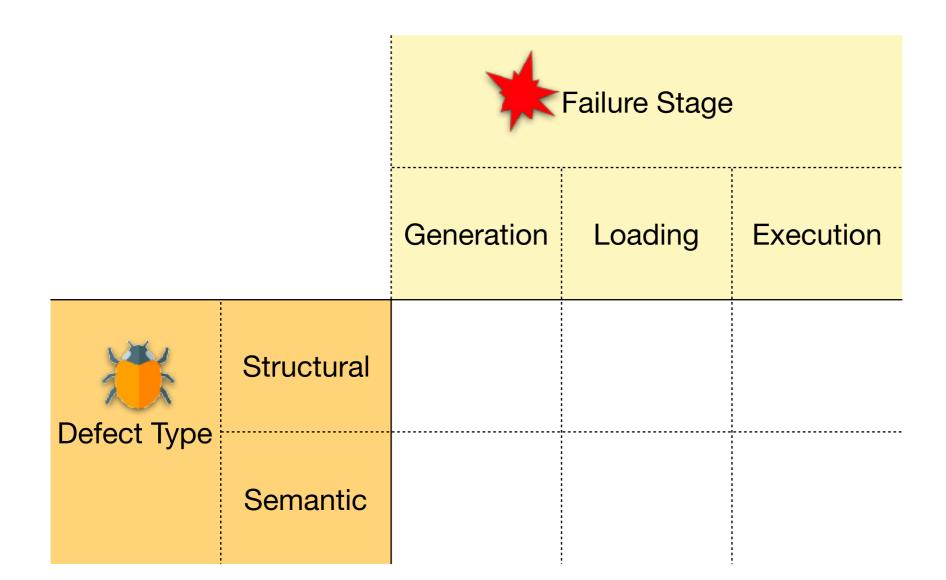
Virtual Machine

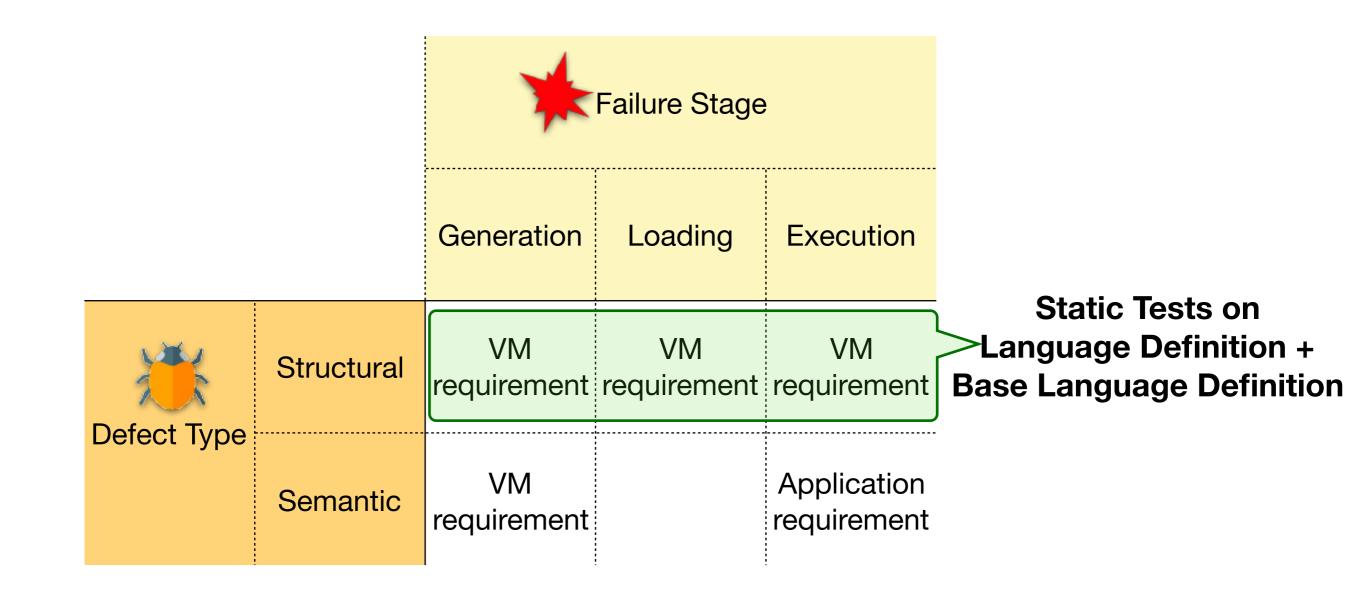
Smalltalk stack dump: 0xbffc8fd0 M >species 0x6e4e350: a(n) bad class 0xbffc7c0c M >copyReplaceFrom:to:with: 0x6e4e350: a(n) bad class 0xbffc7c30 M >, 0x6e4e350: a(n) bad class 0xbffc7c5c I >doesNotUnderstand: activeProcess 0x6e2f7c0: a(n) bad class 0xbffc7c88 I >doesNotUnderstand: activeProcess 0x6e2f7c0: a(n) bad class

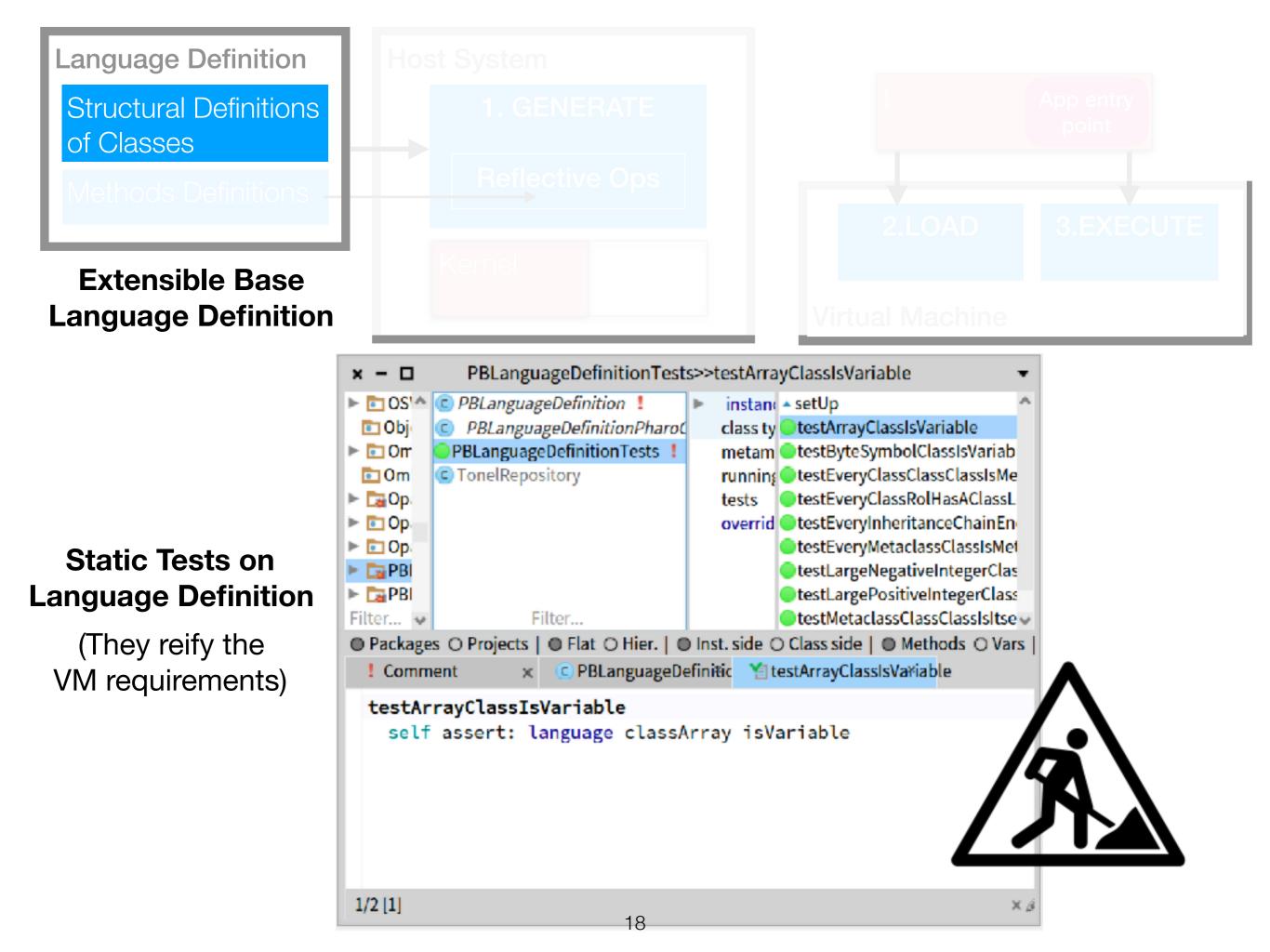
Why is it hard to find the defects back?

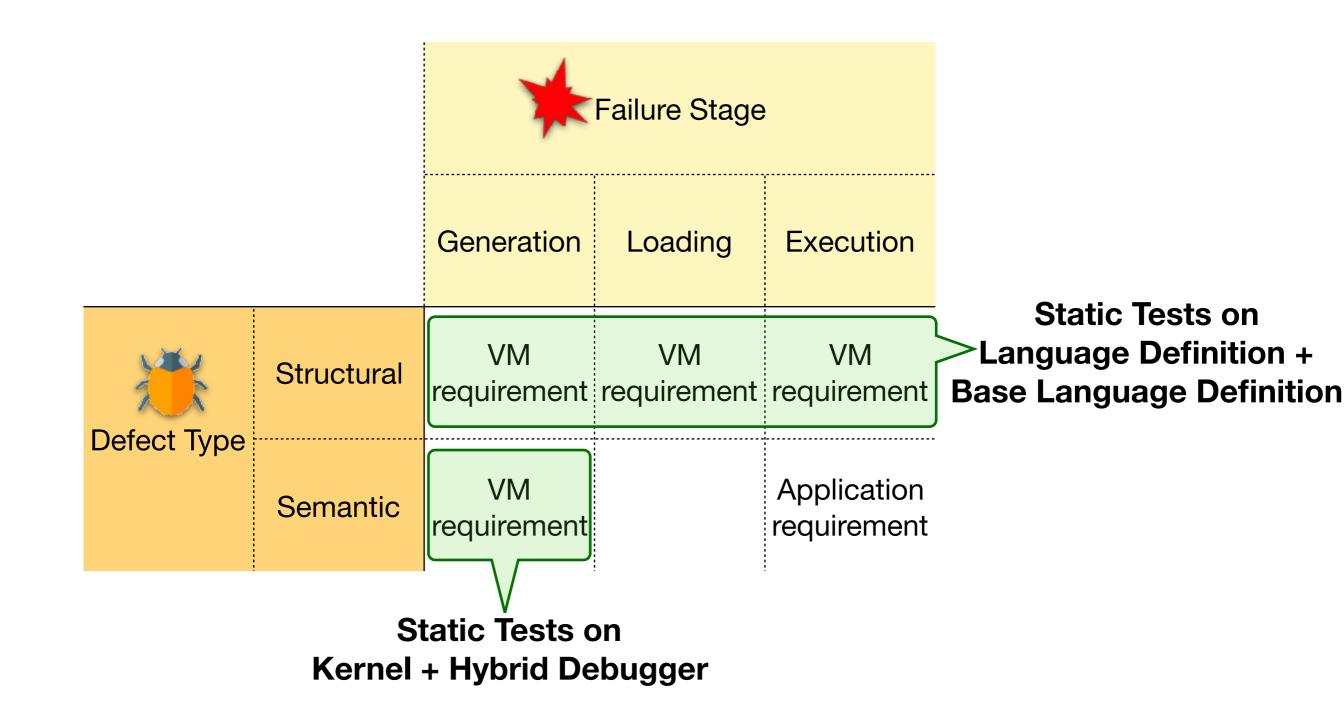
- We are **debugging the VM**
- We lose great part of the abstractions of the generated language

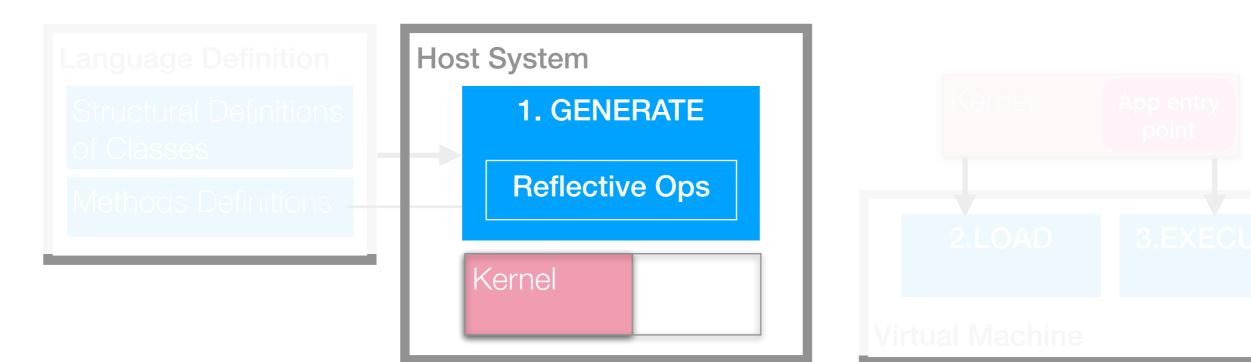
Taxonomy of Errors and proposed Solutions



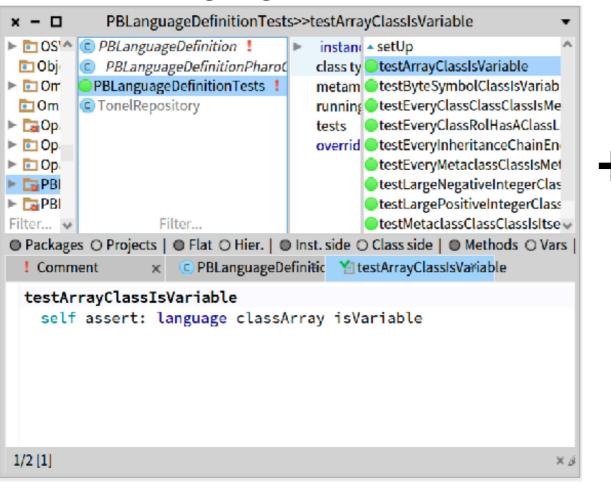








Static Tests on Language Kernel



Hybrid Debugger

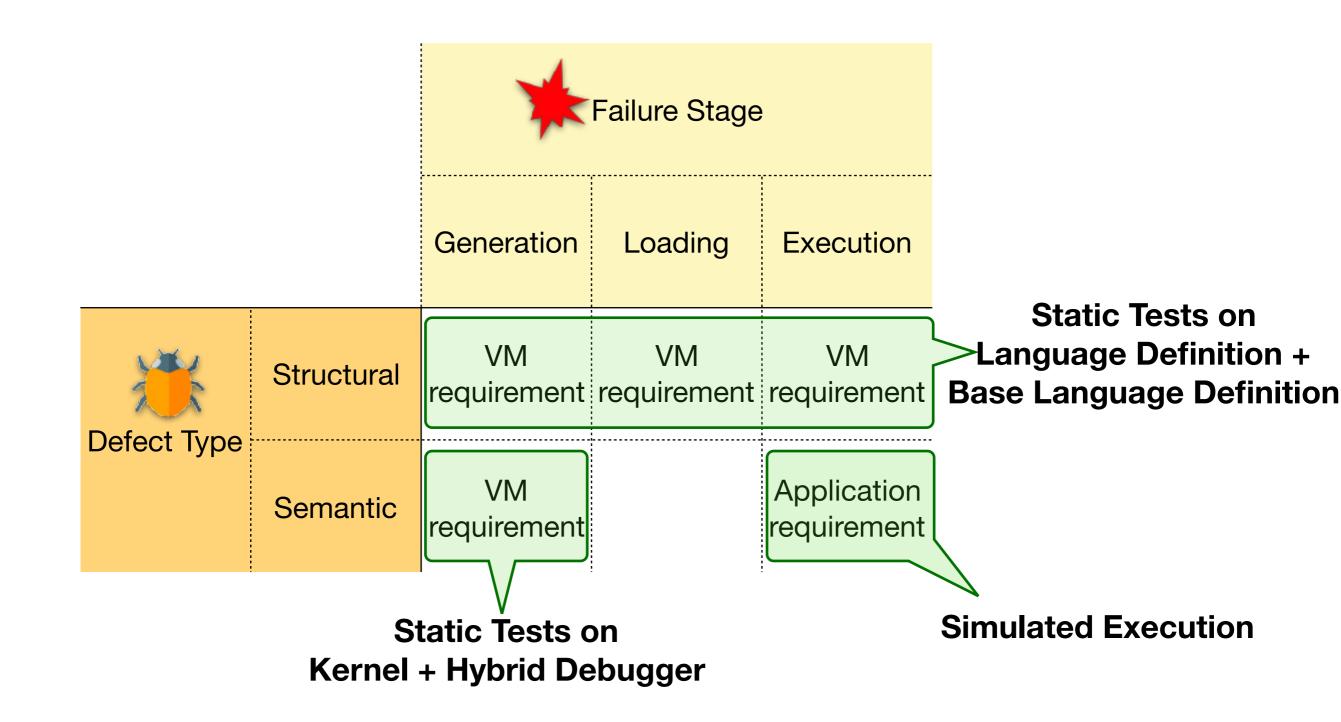
3 Execution levels:

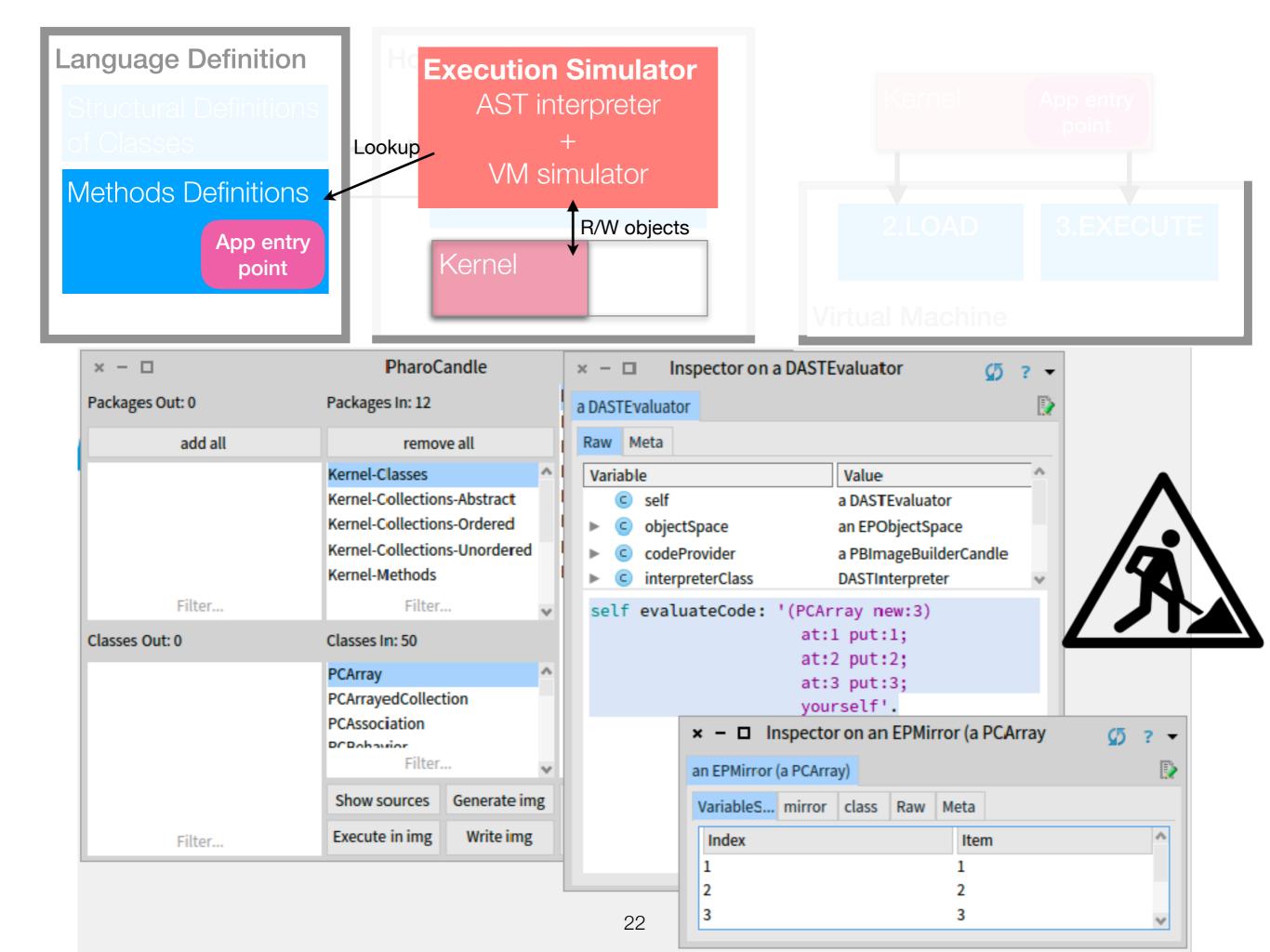
- Language definition code
- Pharo code
- VM code

2 new Debugging Operations

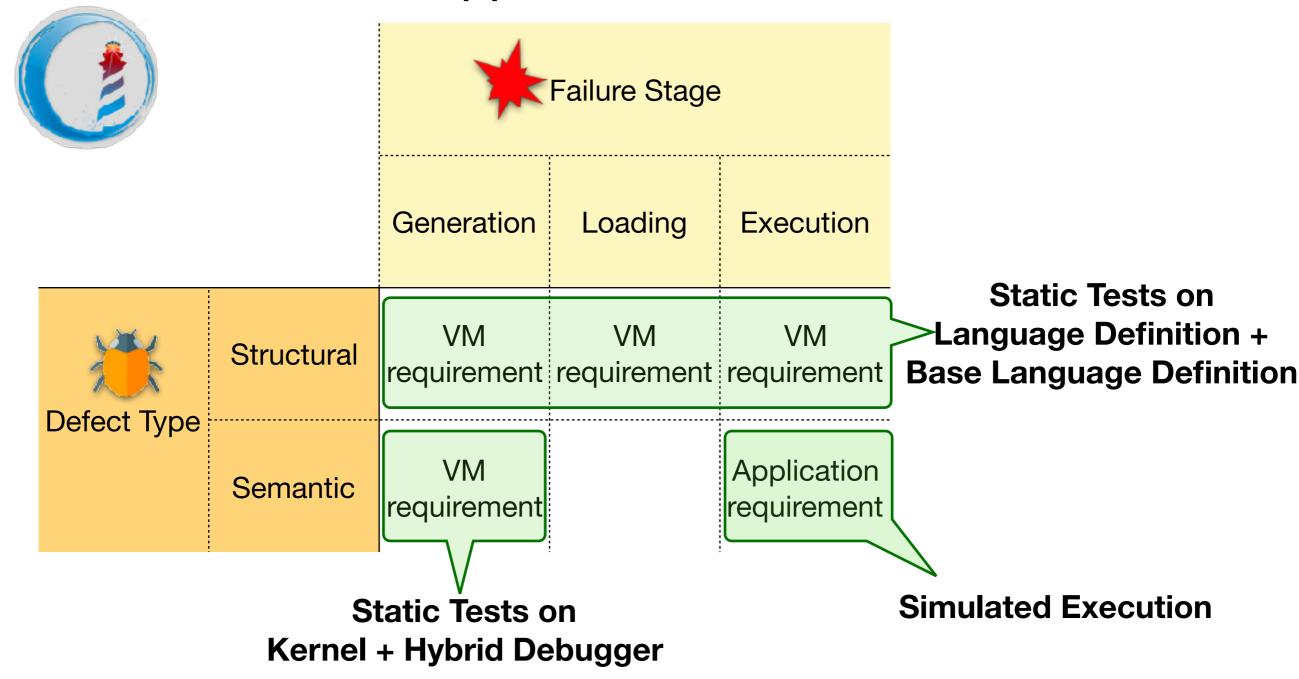
- Step Down
- Step Up







All these solutions can be used to debug the current Pharo bootstrap process!!



Research Directions

- Define the Pharo VM requirements, and model them for future modifications in future VM implementations
- Maximise the flexibility of the extensible base language definition, to maximise the range of languages that we can define from it
- Explore what is a good design for the hybrid debugger, so it contains the correct abstractions for debugging the bootstrap process
- Explore the limitations for the simulated execution environment
- Explore a way to debug failures hard to reproduce and which occur in production environment
- Shrinking the VM by removing unused plugins, which will be determined by dynamically analysing the simulated execution and its interaction with the VM simulator

- Analysis of Pharo Bootstrap process
- Taxonomy of Defects and Failures
- Proposed Solutions for each kind of error

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