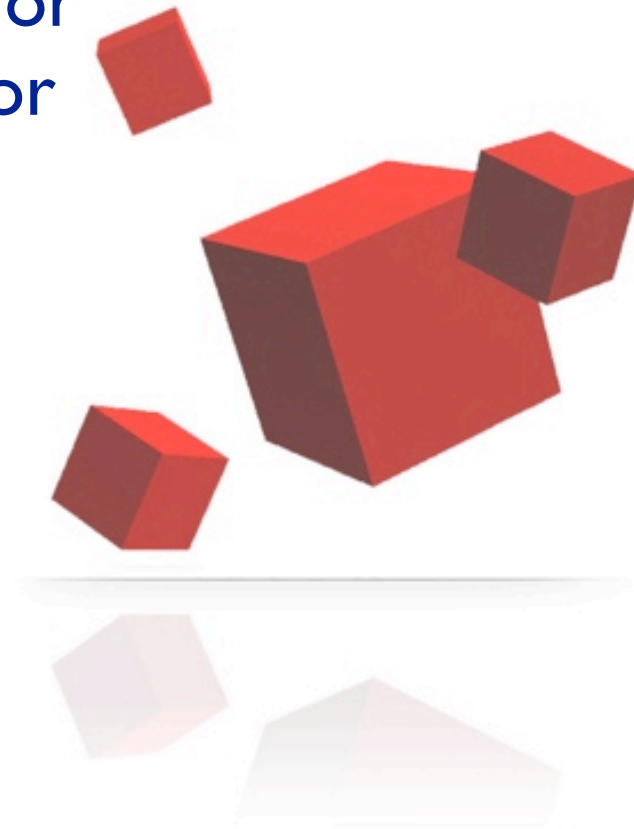


# REALTALK

## A Programming Language for Wireless Embedded Sensor Network

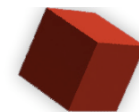
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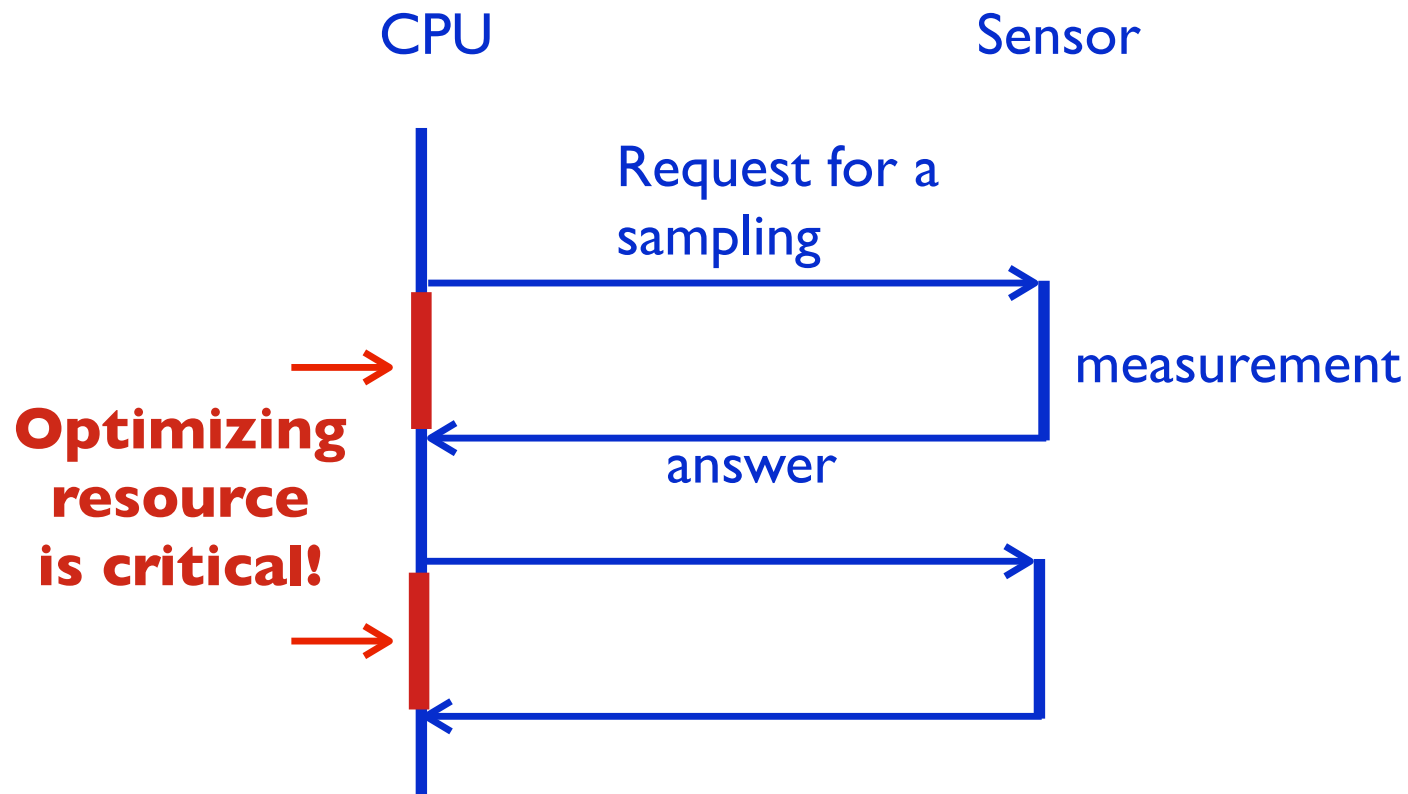


## **Programming wireless sensor devices is difficult**

- Embedded sensor systems are difficult to program.
- Power consumption, memory management, hardware abstraction:
  - component maintenance: the C programming language prevents software component from being easily maintained.
  - sensor asynchronism: sampling is achieved by emitting and receiving events.



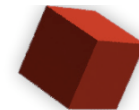
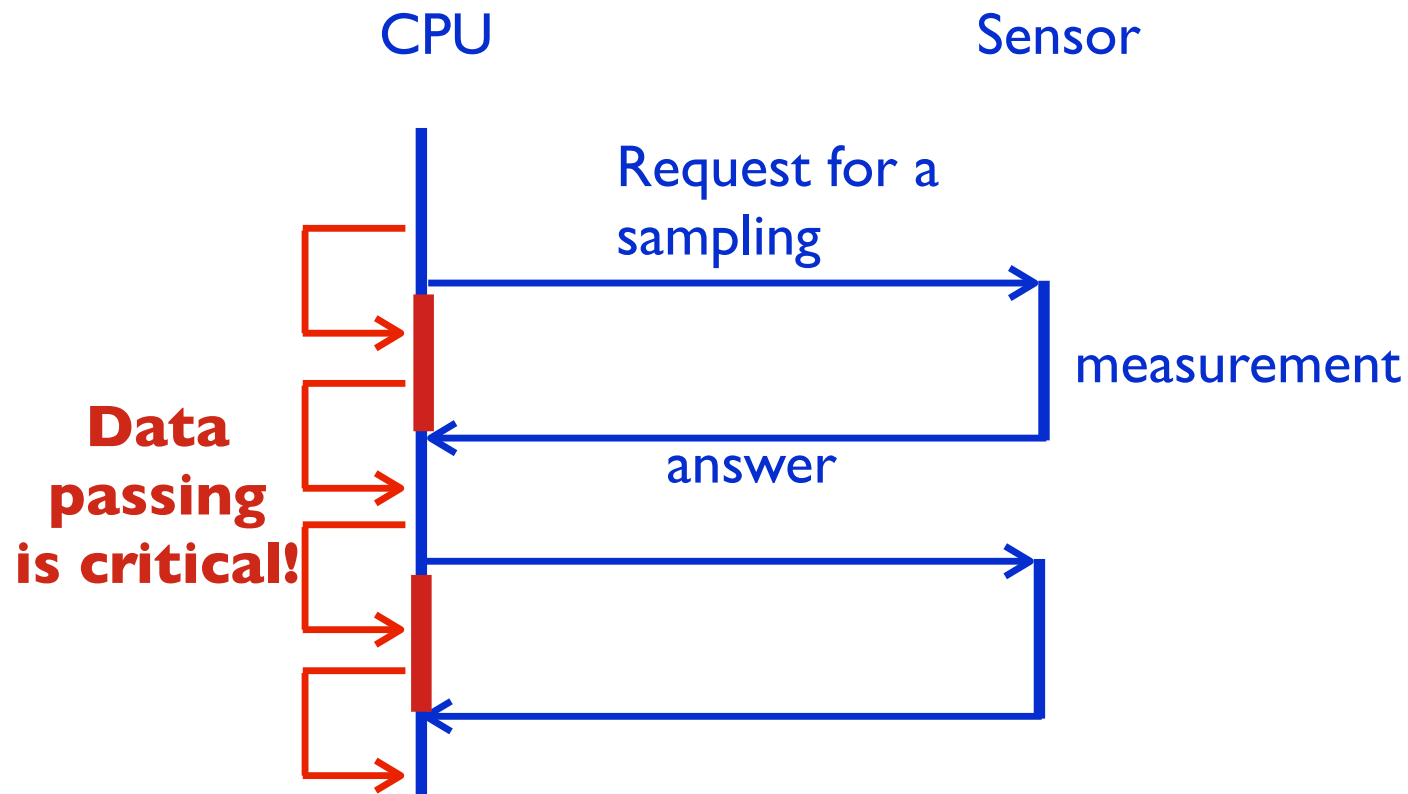
## Sensor sampling creates disruption in the app



**Optimizing  
resource  
is critical!**



## Sensor sampling creates disruption in the app



## Realtalk: An Object-based language

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Goal: making embedded programming easier and providing advanced hardware abstraction.

Creation of a counter application:

```
RTOBJECT subclass: #Counter  
  variableNames: 'leds timer value'.
```

```
Counter compile: 'start  
  value := 0.  
  timer invoke: #triggeredMethod every: 500.'
```

```
Counter compile: 'triggeredMethod  
  value := value + 1.  
  leds display: value.'
```



## Object composition and hybrid type system

---

Linking the counter to the leds and a timer:

```
RTOBJECT subclass: #Counter  
  variableNames: 'leds timer value'.
```

```
Counter composeWith:  
  { #leds -> Leds. #timer -> Timer }
```

Realtalk supports an *hybrid type system*.



## Class specialization

---

Let's emit a sound at each increment:

```
Counter subclass: #SoundCounter
  variableNames: 'sounder'
  aliases: { #triggeredMethod -> #incAndDisplay}.
```

```
SoundCounter compile: 'triggeredMethod
self incAndDisplay.
leds isRedOn
  ifTrue: [sounder start]
  ifFalse: [sounder stop].'
```



## Example of Controlled Disruption

---

Reading two sensors and emitting their sampling:

```
AnyObject compile: 'readingTwoSensors  
| value1 value2 |
```

```
  leds display: 1.  
  value1 := lightSensor read.
```

```
  leds display: 2.  
  value2 := soundSensor read.
```

```
  leds display: 3.  
  radio emit: (value1 + value2).'
```





## Method is cut down into pieces...

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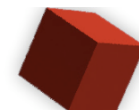
Reading two sensors and emitting their sampling:

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| value1 value2 |
```

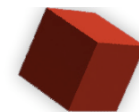
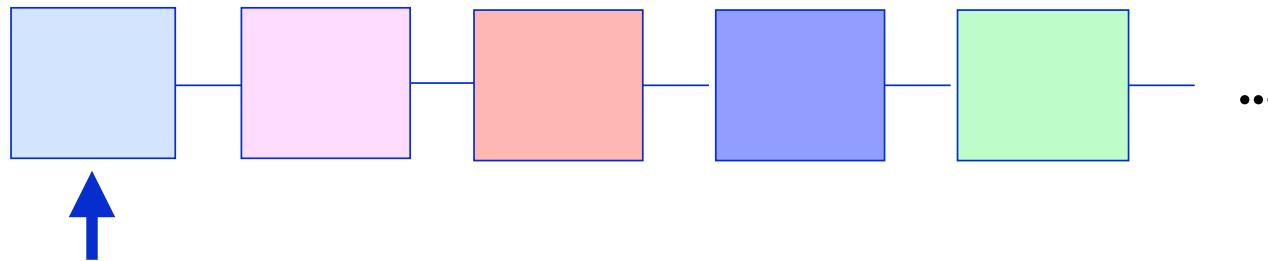
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  leds display: 2.  
  value2 := soundSensor read.
```

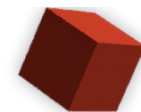
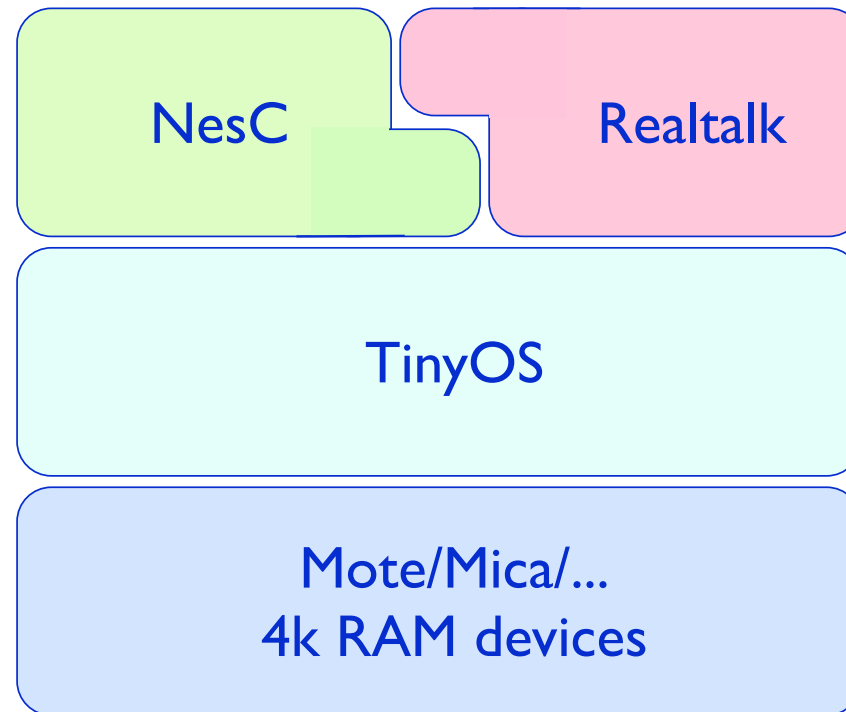
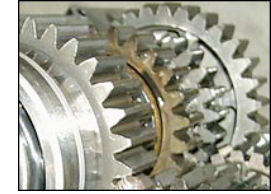
```
  leds display: 3.  
  radio emit: (value1 + value2).'
```



## ... and those pieces are inserted in a pool



# Implementation based on TinyOS/NesC



## Conclusion

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- Realtalk is a scripting language dedicated to small sensor device with high limited resources.
- It provides advanced features regarding:
  - component interactions
  - component specialization
  - sensor programming
- On going work focuses on large software construction.

